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Minimal Rationalism

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Enquiries into the possible nature and scope of innate knowledge never proceed in an empirical vacuum. Instead, such conjectures are informed by a theory (perhaps only tacitly endorsed) concerning probable representational form. Classical approaches to the nativism debate often assume a quasi-linguistic form of knowledge representation and delineate a space of options (concerning the nature and extent of innate knowledge) accordingly. Recent connectionist theorizing posits a different kind of representational form, and thus determines a different picture of the space of possible nativisms. The present paper displays this space and focuses on an especially interesting sub-region labelled "Minimal Rationalism". The philosophical significance of the minimal rationalist option is explored. Two consequences which emerge are, first, that the apparently clear distinction between innately specified knowledge and innately specified structure is shown to be unproductive; second, that there may exist tracts of innate knowledge whose content is not propositionally specifiable.

1. Nativism: why worry?

Sometimes trivial, usually fruitless, the Nativism/non-Nativism debate generally ends not with a conclusion but with a whimper. All parties agree that something important is present in us without being the product of genuine individual learning. All that then remains is to determine *what*. And that, as has been vigorously argued in the past (Fodor 1980), is in the end an empirical question whose detailed answer is not to be determined by armchair philosophical speculation. Most of the published debate thus consists in arguing about whether some of our innate endowment is highly domain-specific (Chomsky 1986) or instead relates to basic, general-purpose problem solving (Putnam 1981). A second major strand of the published debate relates specifically to concepts and revolves around the question whether anything genuinely worth calling concept learning actually takes place, or whether all our conceptual repertoire must be in some non-trivial sense innate (Fodor 1980 and papers in Piattelli-Palmarini 1980).

The present treatment maintains a safe distance from these types of question (a few asides notwithstanding). Instead, the focus is on the way in which the possibility of innate knowledge is conceived. I shall argue that the received conception of the space of possible options is in fact a product of the (often tacit) acceptance of a certain model of the probable form of internal knowledge repre-

sensation: a form whose clearest expression is found in the hypothesis of an innate language-like representational system (a Language of Thought). Change the conception of the form of internal representation and you radically alter (or so I shall argue) the picture of the space of possible options.

This potential alteration has not gone unnoticed in the recent literature. Important treatments include Ramsey and Stich (1991), Narayanan (1992) and Karmiloff-Smith (1992a). Several of the themes I develop in §§2-4, where I discuss the impact of connectionism on the nativism debate, in the broadest terms, are rooted in these exploratory forays. The remainder of the paper, however, tries to push the new debate a little further. Thus §5 introduces (with some simulation results) a largely unnoticed (but see Karmiloff-Smith 1992a, 1992b) yet potentially highly significant possibility which I term "Minimal Rationalism". A minimally rationalist innate endowment involves the (domain-specific) pre-setting of tiny but vital information-processing parameters which, in a delicate co-operation with predictable environmental inputs, result in the acquisition of specific items of knowledge. To understand the nature of such minimal endowments we need to use a new set of tools. Instead of conceptualizing any genuine innate *knowledge* as consisting in familiar kinds of conceptual or propositional content, we need to move towards a more "geometric" understanding. In particular, we need to exploit the idea of an error surface determined by the setting of numerical parameters in a high-dimensional space. The specification of innate knowledge, I shall argue, will often consist (necessarily!) in the fixation of a favourable position on such an *error surface*. Once we thus expand our notion of innate information beyond the realms of what is in principle propositionally specifiable, it becomes increasingly difficult (§6) to separate questions concerning the innate structure (e.g. the local architecture (of layers, modules etc.)) of a computational subsystem from questions concerning innate knowledge. Classical treatments of the nativism debate could support such a separation since they allowed a sharp distinction between computational profile (algorithm and data) and implementation (the underlying physical device). Connectionist approaches erode that distinction and hence blur the difference between structure, algorithm and information.

2. Nativism and representational form

It is no accident that much of the historical debate concerning the pros and cons of nativism revolved around the notion of an innate *idea*. For talk of ideas, vague though it was (and is) nonetheless reflected the best available theory of that in which our *mature* knowledge might consist. And our conception of the potential nature of any innate endowment was, by default, modelled on our conception of the nature of the mature product.

In talking of innate ideas in the mind, we are not yet forced to consider questions concerning any possible physical vehicles for those ideas. In these more rampantly physicalist times, however, questions concerning the possible *contents*

of tracts of innate knowledge have been inspired not just by a vision of the *contents* of the mature product but also by a vision of the *form* of their inner vehicles. The clearest example of this line of influence is seen in the works of Jerry Fodor.

Fodor subscribes to what I shall call "Bipartite Nativism". Such a nativism ascribes two types of innate endowment to the human neonate. These are:

1. An innate (but peripheral) system of processing *modules* which are significantly structured so as to promote the acquisition of specific skills (e.g. grammar acquisition). (Fodor 1983)
2. An innate (and central) corpus of representational atoms (which includes atomic items corresponding to most lexical concepts and which merely require triggering by exposure to appropriate environmental stimuli). (see Fodor 1975, 1980, 1987)

Fodor thus subscribes both to a kind of "gross architectural" nativism (for the modules) and to a "symbolic nativism" (for central processing).

In the following sections I shall try to articulate a very different picture. It is a picture in which the image of the form of representation of mature knowledge (of the kind which Fodor would ascribe to "central processing") is very different. This difference, I shall argue, leads us to reconceive the notion of innate knowledge in important ways and eventually blurs the architecture/representation distinction itself.

3. Connectionism: the bare essentials

The broad lines of the Connectionist Cognitive Paradigm are by now familiar to most philosophers (for introductory treatments see Clark (1989), Bechtel and Abrahamson (1991) and the essays collected in McClelland, Rumelhart and the PDP Research Group (1988) vols. I and II), and I shall risk only a summary introduction here. It is the specific vision of the form of any innate endowment which is going to do most of the work in what follows.

The connectionist approach, insofar as it presents itself as a genuine alternative to classical "rule and symbol" systems, relies on (i) an alternative form of knowledge representation, (ii) an alternative type of basic processing operation and (iii) a set of powerful learning algorithms.

To understand the form of knowledge representation and type of basic processing operation, it helps first to recall the broad lines of a connectionist computational architecture. Such an architecture consists of a mass of idealized "neurons". These are simple processing units capable of receiving inputs from their neighbours, taking on a resultant value (an "activity level" expressed as a number, usually between 0 and 1), and passing on an output to other neighbouring units (the ones on the output side). The relation between the overall inputs to a unit and its output need not be linear (often, a sigmoid function is used). The units are sometimes arranged into layers, in which case a unit in say, the second layer of a three layer network will receive inputs from units in the first layer and send

outputs to those in the third. The first (input) layer may e.g. correspond to sensory inputs, the third (output) layer to motor commands, while the intervening ("hidden unit") layer allows the system to develop internal representations capable of subserving the desired overall input-output profile. Activity is propagated through the network by weighted connections between individual units. The weights modulate the effects of the signals produced by individual units. Weights can be positive or negative, and act so as to amend signals passing along them by a factor determined by the size and polarity of the weight.

Such systems can be used simply to implement familiar "classical" forms of knowledge encoding. But the most interesting sub-class of such systems explore highly distributed encoding schemes. At first glance, the notion of a distributed encoding does not look especially exciting: imagine a system that used 78 units to represent letters of the alphabet, and in which the letter "A" was coded for by the joint activity of units 1, 2, and 3, the letter "B" by that of units 4, 5, and 6, and so on. In such a case, the fact that the representation of "A" was spread over 3 units buys us nothing. The encoding scheme is still *effectively* localist. The representations are distributed in only a weak sense, for the system does not *exploit* their extendedness in any semantically significant way (see Van Gelder (1991) for further discussion).

Distributed encoding becomes interesting only when it is conjoined with the use of a *semantic metric* on the representational space. Thus consider next a representational scheme in which individual units stand for fragments of letterforms (in a given case and font). Thus one unit may code for a high horizontal bar as on a capital E, another for a vertical upstroke as on a capital I etc. The distributed representation of a letter is then just the joint activity of the appropriate letterform fragments ("microfeatures" if you will). This encoding scheme exhibits an attractive property: the fact that a given letterform "F" shares more features with e.g. "E" than it does with "C" will be reflected in the system's use of encoding resources. The "E" representation will involve an overall state of unit activation which overlaps considerably with the "F" representation, while the "C" representation will remain largely orthogonal. It is in this sense that we can speak of some connectionist systems as embodying a semantic metric. The similarity between representational contents is echoed by a similarity between representational vehicles. Within the scheme, the representation of a new item (say "Z") is non-arbitrary. Classical systems exhibit such non-arbitrariness at the level of propositions: whole structures describing states of affairs. Connectionists encourage the non-arbitrariness to percolate deeper, so as to characterize individual referring terms. The key to this is their use of a single resource (set of units and weights) to superpositionally encode several contents in a systematic manner. (For extended discussions of this idea see Van Gelder (1991) and Clark (forthcoming a, Ch. 2)).

Regarding knowledge representation, then, the radical connectionist eschews representations which consist of symbolic atoms concatenatively combined to form symbolic expressions. (For a good discussion, see Van Gelder (1990)). Instead, connectionism exploits activation patterns among large numbers of ide-

alised "neurons" to encode specific contents. The resulting scheme turns out to resemble prototype based encoding insofar as similar contents tend to be represented by similar patterns of activation. All the semantically significant items in such an encoding can thus have significant internal structure. In a very real sense, there are no symbolic atoms here i.e. no items which are both clearly representational and lack semantically significant inner structure. Moreover, complex contents are not represented by concatenations of more basic representations but by new activation patterns (ones which need not literally *embed* the "components") created by processes involving mathematical operations upon the numerical vectors which constitute the "activation patterns". Once again, the departure from the classical paradigm is quite marked (see Smolensky (1909), Fodor and McLaughlin (1991)).

In such systems, the basic processing operations are defined over such numerical vectors. Information retrieval consists in a process of vector completion given a partial vector as a cue. Generalization is achieved by the superpositional storage of activation patterns in a single set of long term *weights*. It is these weights which allow the system, given a partial vector (pattern of activation across a set of input units) as a cue, to complete the vector (by activating, courtesy of the connection weights, a specific pattern of units). If several contents are stored superpositionally in a single network of units and weights, an input cue which is appropriate to several such patterns will induce an activation pattern which in a sense averages the patterns of the individual contents which fit the cue. Hence so-called "free generalization" (see Churchland (1989), Ch. 9).

Probably the greatest achievement of connectionism, however, is to have described and implemented learning rules which cause networks automatically to discover such superpositional storage schemes and hence to impose a semantic metric as a natural side-effect of the process of learning a target input-output function. Thus starting with random weights on the connections a network can automatically alter the weights in a way which should lead it to encode a desired input-output mapping. This kind of learning is usually driven by exposing the net to a set of inputs alongside a set of desired outputs. The net uses the (initially random) weights to yield an (initially hopeless) output. If the output is incorrect, an automatic procedure slightly amends those weights most heavily implicated (along the path of activation between input and output) in the mistake in whatever direction (increase or decrease specific weights) will yield a reduction in a numerical error measure calculated by comparing the actual output to a target output. Such a process (of "gradient descent learning"—see e.g. P. S. Churchland and T. Sejnowski (1992), pp. 106-7) gently leads the network in the direction of an assignment of weights which will support the target input-output mapping and (usually) will generalize to deal with *new* cases of the same type (e.g. a net trained to map coding for written text to coding for phonemes will then perform the mapping for text on which it was not specifically trained—see Sejnowski and Rosenberg (1986), (1987)).

Even such a summary sketch succeeds (I hope) in displaying the genuine distance which separates these connectionist models from their classical cousins. Where classicists were tempted (maybe even forced—see Fodor (1975)) to posit a system of innate symbolic atoms and significant innate architectural structures (the modules of Fodor (1982)) the connectionist may appear ready to reject *both*: to insist on a single network of units and weights and to begin with random weights and hence no ready-made set of symbolic atoms. But this, as other commentators have rightly pointed out (see Churchland (1989), Karmiloff-Smith (1992a), Narayanan (1992)) would be too hasty. The connectionist (like everyone else from behaviourists upwards (see e.g. Quine (1969), p. 96) must often be a nativist too. But the empirical details of the connectionist approach determine a space of nativist options which is importantly different to the classical space. I shall sketch that space, and then proceed to a closer investigation of my favoured corner of it: a subspace I term “minimal rationalism”.

4. The space of connectionist nativisms

The space of possible connectionist nativisms is bounded by two extremes. One extreme is the Connectionist Tabula Rasa: a single, big undifferentiated network which begins with a random assignment of weights. The other extreme is the Connectionist Classical Device: a units-and-weights style implementation of the full bipartite classical story, with innately specified modules and a central system which uses connectionist resources to implement a full classical symbol system. (For a sketch, see Touretsky and Hinton (1985), Touretsky (1989).) The Connectionist Classical device we put aside. It is of little philosophical interest in the present context. The Connectionist Tabula Rasa, although it is shortly to be rejected (on empirical grounds) merits a few initial comments.

First, and most obviously, the connectionist Tabula Rasa (like its associationist ancestors) is not a totally blank system after all. For it comes equipped with both a structure (a specific number of units and weights, and a specific configuration into input layers, output layers and intervening layers) and a learning rule. This is unsurprising. As Samet comments “Even tabulas have some innate structure” (1986, p. 575). The Connectionist Tabula Rasa is not, anyway, to be taken seriously as a model of the human neonate’s cognitive state. A wealth of results in psychology and neuroscience attest to the significant amounts of additional innate structure upon which human cognition relies (see e.g. Churchland and Sejnowski (1992)). Working connectionists have come to appreciate more and more the need to pre-structure networks to perform complex tasks—see e.g. Plunkett and Sinha (1992), McClelland (1989), Le Cun et al. (1989). All that said, there is still an important existence proof embodied in the Connectionist Tabula Rasa viz that something at least closely akin to *rational/causal concept learning* is, *pace* Fodor (1975, 1980), quite definitely possible without the aid of a ready-made set of symbolic atoms with which to formulate explicit hypotheses.

It is easy to see why this is so. Fodor’s image of cognitive change distinguishes sharply between true learning (a rational process in which what is learned depends systematically on the *contents* of inputs to the system) and other kinds of change. A Latin pill, or a bang on the head, might induce new cognitive skills of change. A Latin pill, or a bang on the head, might induce new cognitive skills in us: but the process is not a rational one, hence not a true case of learning (see e.g. Fodor (1980), p. 275). Famously, Fodor depicts the *basic* representational resources of a system as a set of symbolic atoms—items which bear specific contents and need only to be *triggered* by a minimal environmental input. Thus a specific stimulus, like a red dot on a beak, can trigger an entire complex behavioural pattern in an animal—the pattern is not plausibly viewed as *learnt* by some rational means involving reflection on the stimulus: an extreme case of the “poverty of the stimulus argument”! Real learning for Fodor, occurs only later, when a system can use existing representational resources to formulate a hypothesis (e.g. about the meaning of a lexical item) and test it against experience.

A connectionist network which begins life with a random set of weights (and no task-specific fancy architecture, see §5 below) and learns a generalizable mapping by exposure to a set of training cases amounts, I claim, to a case in which we have genuine learning without innate symbolic atoms. It is genuine learning because the acquired mapping is specified in, and acquired in virtue of, the specific inputs to which the net is exposed. It is not like merely triggering a knowledge representation already present in the net. The learning is achieved without relying on the “*contents*” of whatever random activation patterns the net was initially disposed to produce in its efforts to acquire the target mapping. To establish this last point, reflect (1) that the initial weight assignments, being random, may embody no usable knowledge at all and (2) that the process of weight change is not a process in which existing representational elements are concatenated to express putative target knowledge items.

It is easy to miss this powerful result. It escapes notice if we adopt a common misreading of Fodor’s claim. The misreading depicts Fodor as claiming only that representational potential cannot increase (which is surely true) and that learning involves the testing of hypotheses. It is then all too easy to visualise the network as performing a kind of numerical “hypothesis generation and test” in which

the test is the measure of network performance (such as sum-squared error) and the procedure for generating new hypotheses, given the successes or failures of past hypotheses, is given by the learning algorithm. (Christiansen and Chater 1992, p. 42)

The point to notice, though, is that the network’s early “hypotheses” are not framed using a set of symbolic atoms nor (a fortiori) is the potential representational scope of the network *bounded* by the representational power (under processes of expressive recombination) of such a set of initial representational atoms.

To repeat, the Tabula Rasa case provides a genuine proof of the ability of some systems to engage in *rational* knowledge acquisition without an innate representational base. For such networks do not acquire knowledge by accident, or by simple triggering. They learn what they learn as a consequence of the specific

contents of the training set. The connectionist is thus able to offer a genuinely *empiricist* vision of learning which is nonetheless not (*pace* Fodor (1980), p. 279) committed to the use of hypothesis generation and test defined over a set of antecedent (hence unlearned) symbolic atoms.

The existence proof of rational knowledge acquisition without any innate representational base in place, we move on to probe the more empirically plausible regions in the space of connectionist nativisms. This subspace (between the *Tabula Rasa* and the Connectionist Classical Device) has recently been divided (Narayanan 1992) into two parts. One part encompasses various forms of what Narayanan (after Fodor (1983)) calls "Architectural Nativism", viz. the innate specification of gross structural properties such as division into modules etc. The other part encompasses what Narayanan (1992, p. 80) calls "Representational Nativism", viz. a nativism of contents or methods of representation.

The basic idea is that the stored connection weights constitute the knowledge of a network and hence that pre-setting these amounts to building in real knowledge. By contrast, the gross *arrangement* of units and weights (numbers of units, of layers, modules etc.) constitutes the form of the processing device. Pre-setting these latter parameters may help solve certain problems but falls short of building in real knowledge. I suspect, however, that the architectural/representational distinction is not, in fact, a reliable taxonomic device, as we shall soon see.

Suppose a connectionist wishes to escape the paradigm of "tabula rasa" learning and to give her network a helping hand (e.g. because the target mapping is too hard, or because the training data is too skimpy, or because the net needs to solve the problem without an extended period of training). There are various options, the most important being:

1. Hand-coding of weights.
2. Choice of local or global architecture.
3. Data manipulation.

Hand-coding of weights is the most obvious, but probably least practical solution. For small problems, it is possible to pre-set connection weights either (a) to solve the problem or (b) to speed up the process of *learning* to solve it (much more on this later). More usual is the practice of choosing a gross architecture (e.g. a division into modules (Norris 1990) or the arrangements of layers and units within a module (McClelland 1989)) which is in some way suited to the target task. Thus Norris (1990) describes an arrangement of three distinct subnetworks which together neatly solve a problem (idiot savant data calculation) which visibly decomposes into three parts. A single, undifferentiated net, presented with identical data, was unable to solve the problem.

A final and less widely noticed alternative is to manipulate the training data. Thus it can be demonstrated that the kind of result Norris achieves by pre-structuring the net can also be achieved by a careful structuring of the training data. Elman (1991) describes a grammar acquisition problem which defeats a single network until the training data is divided into several distinct batches, each batch prompting the net to solve a sub-problem whose solution reduces the complexity

of solving the sub-problem presented by the next batch. Manipulating the training data thus effectively decomposes the single intractable problem (learn mapping X) into a sequence of tractable subproblems (learn mapping P , then Q , then R) whose cumulative effect is to solve X . (I discuss the above cases in detail in Clark (forthcoming a) Ch. 7.)

It is not immediately obvious, however, that this last case (data manipulation) represents a plausible variety of innate knowledge. In fact, it does, since the data manipulation (which effectively alters the statistical distribution of input data over time) can be achieved automatically! This involves allowing the net to see fully mixed (i.e. unbatched) data but providing it with a kind of selective filter in the form of a short-term memory which gradually expands over time. The limited window on the data which the initial (most restrictive) memory allocation provides results in only the short, simple grammatical structures being actually available to power learning. As the window expands, more complex structures become "visible" to the net. The overall effect is just as if the data had been carefully divided into batches.

The immediate point to notice is that there is an important sense in which all the above means of "helping" a network are functionally equivalent. Thus the beneficial effect of a piece of hand coding of weights may lie in the way those weightings effectively modularize the network, channelling certain inputs to one group of hidden units and others to a different group. (For a working example, see the discussion of the balance beam example in Plunkett and Sinha (1992).) Similarly the result of Norris' architectural pre-structuring is to promote a certain problem decomposition: an effect which can also be obtained by manipulating training data or short-term memory. It can also (see §4) be obtained by evolving weights which enable the net to reorganize the training data for itself.

In and of themselves, these functional equivalences, though initially surprising, are not evidence of anything genuinely unfamiliar. It is a commonplace of the classical paradigm that a given input-output behaviour may be achieved either by "hard-wiring" the system (directly manipulating the *processor*) or by creating a program (manipulating the *representations*). It is therefore important to see that the connectionist equivalences just sketched flow from a different, and deeper source. For what underlies these equivalences is the profound interpenetration of representation and processing within the connectionist paradigm. It is worth pausing to clarify this.

The fundamental root of the equivalences (between hand-coding, data manipulation and gross structural pre-organization) lies in the fact that connectionist models do not embody a firm distinction between representation and processor. Processing in these systems involves the use of connection weights to create or re-create patterns of activation yielding desired outputs. But these weights, as we saw, just *are* the network's store of knowledge. Changes to the knowledge base and to the processing device (the web of units and weights) go hand in hand. As McClelland, Rumelhart and Hinton put it:

The representation of the knowledge is set up in such a way that the knowledge necessarily influences the course of processing. Using knowledge in processing is no longer a matter of finding the relevant information in memory and bringing it to bear: it is part and parcel of the processing itself. (1986, p. 32)

Whereas, from a classical perspective, it makes perfect sense to clearly distinguish between innate *architectural* facts and innate *representational* facts, it is by no means clear that the distinction can bear much weight (*pace* Narayanan's taxonomy) in a discussion of connectionist nativisms. All there is to manipulate are unit and weight arrangements, and unit and weight parameters. Since these just *are* the system's encoding of knowledge, it makes little sense to treat them as "mere architecture". On the other hand, since there is no separate processing device apart from these unit and weight settings, it makes little sense to treat them as purely representational either. Nor will an appeal to transient versus fixed structure solve the problem. It is true that it is common to keep an arrangement of units, layers etc. fixed and allow only the weights to change. But it is not necessary. Learning can and often does involve processes which add or delete connections (see Mozer and Smolensky's (1989) discussion of "skeletonization") and we know that real synaptic growth and loss is sometimes a feature of learning in the brain. In fact, the difficulty of drawing a firm distinction between architecture and representation becomes quickly apparent when we turn to real brains (see Churchland and Sejnowski's (1992), p. 177) discussion of the difficulty of distinguishing between information and the channel which "carries" the information in real brains). It is the influence of the classical computational paradigm, with its (generally) neat divisions between program and stored data (and between algorithmically important detail and "mere implementation detail" (see Fodor and Pylyshyn (1988)) which leads us, mistakenly, to try to conceive of knowledge representation in connectionist systems in the same way. In reality, connectionist approaches erode the structure/knowledge divide and make it an unhelpful instrument with which to orchestrate the debates.

The best we can do, I suspect, is to treat each case individually and ask ourselves whether this or that specific pre-setting of weights or pre-structuring of gross architecture is best thought of as building in some item of knowledge or not. In general, the difference between hand-coding of weights and pre-structuring of gross architecture reflects if anything a difference in the generality of the innate knowledge. Thus provision of a tripartite modular architecture may effectively build in some very general knowledge about the domain, e.g. that it presents a problem whose decomposition has three distinct parts, whereas hand-coding of weights can build in much more specific items of knowledge.

Having now sketched the most obvious (and, as it happens, pretty much equivalent) ways in which a connectionist may go "nativist", the next step is to explore in detail a specific option which constitutes the most novel and interesting region of the new space.

5. Minimal Rationalism

It is the rationalist who, somewhat paradoxically posits the greatest non-rational element in human cognitive development (see Fodor (1980), p. 273). Whereas the empiricist believes that cognitive development relies largely on intelligent procedures whose aim is to make sense of perceptual inputs, the rationalist depicts a large chunk of cognitive development as turning on non-rational "brute-causal" processes. The clearest case of such a process involves the triggering of a complex behavioural repertoire by a simple stimulus e.g. the sighting of a red dot causing feeding behaviour. The gap between the stimulus and the response is such that no conceivable process of ratiocination could extract the plan for the behaviour out of the stimulus alone. It is not given *in* the stimulus—merely triggered *by* the stimulus. Contrast, for example, NETtalk's acquisition of knowledge about text→phoneme mapping (Rosenberg and Sejnowski 1987). This knowledge can sensibly be depicted as given in the training data (a corpus of correct sample text→phoneme mappings). Hence NETtalk falls on the empiricist side of the divide.

The rationalist posits innate endowments which enable us to go way beyond what is (in some elusive but intuitive sense) available in the data alone. In practice, this trick is always domain-specific, e.g. Chomsky's rationalist model of grammar acquisition, Fodor's of concept-acquisition etc. The reason is interesting and merits a momentary detour.

Try to imagine a *domain-general* rationalism! It would have to involve strategies which successfully go beyond the data in *any* domain. But how could this be? For to go beyond the data *means* to reach conclusions not reachable without *specific* pre-information. Any principles which successfully apply to *any* domain must therefore be exploiting information implicit in the data and/or relying on completely general facts about the structure of our universe. Mechanisms exploiting these kinds of regularity fall clearly into the empiricist camp. So rationalism is by *definition* domain-specific: it is the claim that a being is innately appraised of specific items of information which contribute to its success in specific domains. Domain-general "rationalism" thus collapses into empiricism.

Rationalist approaches have in the past been characterized not just by domain-specificity but also by a richness of domain-specific information. But such richness, unlike domain-specificity, seems in no way conceptually essential. It is perfectly possible for a being to go beyond the data, in vital ways, courtesy of what I shall call a Minimal Rationalist innate endowment. It is this option which, I claim, connectionism offers us a currently unique opportunity to explore. In its more general form, Minimal Rationalism is characterized as follows:

Instead of building in large amounts of innate knowledge and structure, build in whatever minimal set of biases and structure will ensure the emergence, under realistic environmental conditions, of the basic knowledge necessary for early success and subsequent learning.

I here use the term "Minimal Rationalism" for the doctrine labelled "minimal nativism" in Clark (forthcoming a). The reason is simple: Minimal Rationalism better captures (for reasons just developed) the detailed flavour of the proposal. And it distinguishes the position from the one marked by Ramsey and Stich's (1991) use of "minimal nativism" as a label for a very different doctrine.

Connectionism's special contribution to understanding the space of Minimal Rationalism lies in its easy ability to combine data-driven induction and tiny domain-specific biases which help drive the inductive process in a desired direction. A clear example of this, which also introduces the important notion of an *error surface*, is the famous problem of exclusive-or (XOR).

The exclusive-or problem is simply this: find a network which, if trained on a database of cases in which the input-output mapping is given by the truth table for exclusive-or, will learn to compute that function, i.e. to output true if and only if at least and at most one of the disjuncts is true. The famous complication here is that no simple two-layer net (comprising two input units and one output unit corresponding to the inputs and outputs specified by the truth table) can learn to solve this problem. This is in marked contrast to other functions (like "and" and "inclusive-or") which can be learned by simple two layer nets. The reason is simple: the XOR problem is in an important sense "higher order"—it involves an operation performed on the output of an inclusive-or function, viz. the net must solve for inclusive-or and then check to see if both disjuncts are true (in which case the output must code for false). This can be accomplished by e.g. adding two hidden units (i.e. a two-unit layer intervening between input and output) one of which acts as a feature detector for conjunction (both input values coding for true) and can inhibit the output coding for true in such cases. All this is no doubt boringly familiar (see P. S. Churchland and T. Sejnowski (1992), pp. 107-11 for a full discussion). But we are not home yet.

So far, the XOR example illustrates the need for a certain configuration of units and connections if the problem is to be soluble. But in practice we need a little more. This is where the notion of an error surface becomes important.

Connectionist devices learn by adjusting the connection weights most responsible for each incorrect output. We can picture the achieved state of knowledge of such a system as a point in a space which has one dimension for each connection weight. The learning task is to move to a location in weight space which will determine the desired input-output mapping. Change the position in weight space and (*ceteris paribus*) you change the system's knowledge, for better or worse. Learning thus consists in a gradual movement within weight space with each step designed to reduce the error signal. It is helpful to picture this process as motion relative to an error surface. Thus imagine a high dimensional space in which one axis (the vertical, say) represents amount of error. The other axes (the horizontals, one per connection) represent the weights. The values of all the weights at a given time determine a specific overall error and hence a specific point relative to this error landscape. When the weights change, the location of this point changes. The goal is to move the point to a location at which the error is as small as possible.

For some problems, such an error surface has a simple, basin-like shape with a single minimum. In these cases an error minimization procedure, such as that provided by back propagation, is guaranteed to find the best solution as it will drive the point (defined by the weights) downhill, reducing error at each step and hence bringing the net ever closer to the bottom of the basin. Other problems, however, define rather different and more problematic surfaces. Thus imagine an error surface whose shape is not a concave basin but instead is more like a mountain range with several peaks and intervening troughs of varying depths. The minimal possible error corresponds to the deepest trough. But a particular set of initial weights may determine a point in weight space which is separated from that deepest trough by one or more intervening (less deep) troughs. To reach the target, these troughs and the uphill slopes which follow them, need to be traversed. But a weight change procedure which seeks always to move ahead by reducing the error signal will clearly not get beyond the first intervening valley. To move on would necessitate going uphill and hence briefly increasing the error signal. In such cases things have to get worse before they get better.

The important fact, for our purposes, is that the error surface for the XOR net described earlier is of the "difficult" stripe involving what P. S. Churchland and T. Sejnowski aptly describe as "ravines and assorted potholes" (1992, p. 111). Suppose, then, that a great selective advantage will accrue to any net which solves XOR: how are we to promote success? Otherwise put, how might evolution "fix" things so that a network embedded in a given organism gains the posited selective advantage?

One brutal and maximal option is to hand-code the solution. The absolutely minimal option is to provide the necessary architecture (i.e. include hidden units) and hope for the best (i.e. hope that the network is not led into a local minimum). Alternatively, we might include some general procedure to escape local minima, e.g. allowing much larger weight changes; but such solutions impose other costs (e.g. missing the right solution by oscillating between two points in weight space when the solution lies smack in between). In practice, connectionists opt neither for the absolutely minimal (and failure-prone) option nor for the domain-general (and also failure-prone) option. Instead, they act as *Minimal Rationalists* and indulge in a small amount of weight fixing whose effect (given that problem and that error surface) is to ensure successful learning given the training data. As it happens, the solution in this case is to avoid large initial weights. As long as the initial weights are small, any random distribution of such weights turns out to determine a position on the error surface from which a solution is safely reachable (see P. S. Churchland and T. Sejnowski (1992), p. 111). (As an aside, it seems likely that similar effects, for other problems, could be achieved by constraining specific weights to be positive and others to be negative—a type of innate structuring known to be present in the brain.)

Here, then, is a simple case of Minimal Rationalism in action: pre-set some of the initial weights so as to determine not a solution to a specific problem but a location (on the error surface defined by a problem/data pairing) from which a

solution can be reached, given realistic input data, by an error minimization procedure. Such a location may be specified in detail (if we fix a specific set of weights) or in general (if we simply fix the parameters within which "random" weightings are to be assigned).

If we now pause to ask after the precise *content* of the innate knowledge contained in, say, a specific assignment of weights supposed to determine a favourable point on an error surface, we are in for a surprise. Such an assignment of weights will not in general encode any knowledge at all, at least not of a familiar, propositionally specifiable kind. We cannot specify the content of the position in weight space by reference to a mapping which involves real or imaginary objects properties and relations (such as tables, chairs, unicorns, loving etc.). This contrasts with many trained up networks whose acquired knowledge we can at least gesture at using familiar propositional resources (e.g. the XOR net knows about exclusive-or, NETalk knows something about graphemes and phonetics, the net described in P. M. Churchland (1989) knows about rocks and mines etc.). Nonetheless, it is clear that the advantage which the favourably located net enjoys is in a real sense *informational*. It "knows" things which stop it from inducing certain conclusions (corresponding to dangerous local minima) from the training data. The effect is not unlike the building-in of specific *heuristics* to govern induction in a domain (as in e.g. the BACON models of scientific discovery—see Langley et al. (1987)), except that (unlike the BACON heuristics) the contents in the net case are not obviously specifiable using the resources of English or any other natural language.

The question also arises whether a net which starts in a minimally favourable location on the error surface (i.e. far from the solution but without intervening local minima) should best be counted as an exemplar of empiricist or of rationalist cognitive development. If we follow Fodor's idea that the better the inductive basis the less rationalist the procedure (Fodor 1980, p. 280) we must count the case in hand as perilously close to empiricism! After all, the training provides a firm inductive basis for any net which avoids the minima. On the other hand, the type of initial weight manipulation needed to avoid the minima is problem specific—and problem specific innate endowments move us into the familiar space of rationalisms. The case described is interesting just because it so neatly straddles our accepted categories—hence the label of "*Minimal Rationalism*".

Phylogenetic fixing of a minimally favourable location on an error surface does not, however, exhaust the Minimal Rationalist arsenal. For a principal device has yet to be introduced. This involves the possibility of complex interactions between small initial biases and received environmental inputs to yield specific cognitive competencies. A nice example of such potential for cooperation is given in Karmiloff-Smith (1992a). It concerns the well-established and presumably innate tendency of the human neonate to attend to face-like stimuli (see Johnson and Morton (1991)). In what might such an innate tendency consist? Are the details of the human face already encoded in the weights of some sub-network at birth? Not necessarily. A more minimal possibility is that what is innate is just

a mechanism which detects the presence of "three high-contrast blobs in the position of the eyes and the mouth" (Karmiloff-Smith 1992a, p. 256). The provision of such a mechanism at a point upstream (close to the sensory inputs) on a certain neural pathway will have dramatic effects on the development of resources downstream (deeper in the brain) from such a "gate". For the provision of the minimal gateway sets the scene for the subsequent data-driven development of a module specialised for face recognition. The innate tendency to selectively filter in "three blob" style stimuli will cause the cortical circuits downstream from the gate to receive training inputs which (given the child's actual environment) are heavily dominated by human faces. Such circuits will then learn to *become* specialised for human face recognition. Such solutions will surely appeal to evolution, which is one of the laziest of designers (see e.g. Jacob (1977), Clark (1989) Ch. 4). Once provided with an innate mechanism which acts as a three-blob gateway, evolution can sit back and let the data carry the rest of the burden. Notice also that the provision of such a gateway effectively reconfigures the statistical profile of the input data. Thus suppose faces in fact comprise just 10% of a child's visual input. Ordinary connectionist learning could easily fail, under such conditions, to yield sophisticated face-recognition strategies. But now consider not the gross inputs (to the system/child) but the effective inputs to a specific downstream neural network. If the net is downstream from the three-blob gateway, the inputs here are likely to be 99% dominated by human faces. A network subject to such a barrage will quickly and efficiently learn to become a face-recognition device.

Minimal Rationalism thus places much faith in the gentle manipulation (by small initial biases) of the way incoming data is *taken* by an organism (i.e. the way it is selectively filtered and sent to various locations in the brain). This complex interaction between small innate tendencies and external inputs is most reminiscent (as Karmiloff-Smith notes) of Piaget's (1955) notion of an "epigenetic" interaction between training and innate tendencies, except that it allows for domain-specific innate biases of a kind inimical to Piaget's ideas about general purpose learning (Karmiloff-Smith 1992b, Ch. 7).

A final example should establish the full potential of the Minimal Rationalist option. It involves the *combination* of the "error-surface" manoeuvres and the idea of innately specified reconfigurations of the input data. The example is drawn from a simulation due to Nolfi and Parisi (1991). The task is to "evolve" an artificial organism which will be capable of *learning* to find food in a simulated world. The "organism" (a computer simulation) receives "sensory" input which specifies the location of nearby food. It must learn to take this information and use it to generate motion commands which will move it to where the food is located, so it must learn a general "sensory-input→motion towards food" mapping.

One solution would be to use ordinary connectionist "tabula rasa" learning. This works here. But a drawback of such learning is its *supervised* nature: the error signal is driven by knowledge of what the *right* answer would be. This kind

of supervision is often biologically unattractive. All too often we don't know what the right answer would be until we've found it!

An alternative is to use so-called "genetic algorithms" techniques to *evolve* a solution. In this approach, a multitude of different networks (ones with different, but random weights) are tried out. The most successful are allowed to reproduce (with minor weight variations) to form a new generation. The process is repeated until good eating is achieved. Such a technique could also succeed (see papers in Meyer and Wilson (eds.) 1991). But it, too, has a cost: evolution is required to "hard-wire" the complete solution to the problem, a strategy that is both inflexible and expensive. If a cheaper (lazier) solution were available, there is reason, as we remarked earlier, to suppose it would be preferred.

Nolfi and Parisi found just such a solution. Instead of having the evolutionary process operate directly on a set of units and weights leading to motion commands, they allowed evolution to operate on a different set of units and weights whose task was not to give motion commands but to *train* a net which does. The organism thus comprised two sub-nets, called the standard (motor control) net and the teaching net. The teaching net and the standard net received the same inputs ("sensory" data). The standard net was allowed to learn in the usual, supervised way. But instead of depending on prior knowledge of the right answers to generate the target output relative to which the error signals are computed, it received target outputs from the teaching net. The genetic algorithms approach was then taken. This allowed the evolutionary process to progressively select organisms whose internal teaching nets did the best job of generating training signals which would lead the overall organism to ingestive success. The process succeeded. After about two hundred generations, each comprising a hundred organisms, ingestive success was achieved.

A reasonable fear, at this point, might be that nothing much has been achieved by the evolutionary detour involved in the selection of an auto-teaching capacity. Perhaps all that has happened is that the teach net has evolved so as to solve the "ingestion maximization" problem and the standard net then copies this evolved solution, in which case there is no real gain over the straightforward method of genetic evolution.

The actual situation is much more complex and interesting. To bring this out, consider the following two results. First, Nolfi and Parisi compared the eating competence of a mature evolved, auto-teaching organism to that achieved by a matched control simulation relying solely on evolutionary learning (i.e. using only the standard net). The competence of the auto-teaching network turned out significantly to exceed that displayed by the control simulation. Second, it was possible to show that the competence displayed by the standard net (in the auto-teaching organisms) after the teaching regime actually *exceeded* that of the teacher! Thus in a test simulation organisms' motions were directly controlled by the outputs (the teaching targets) from the teaching net of a successful organism. It transpired that the teach net's own evolved know-how fell short of that achieved by its associated student (standard) net by a margin of some 150 food

items per lifetime. This is probably because there is sometimes a difference between an optimal *target* output and an optimal motion: the most effective target, for teaching purposes, need not always be the best action. To see why this is so and to complete our explanation of the simulation results, we need to look a little more closely at the role of the initial weights and the process of learning.

In a control simulation designed to rule out the possibility that genetic evolution had built the correct solution directly into the standard net (and hence was not exploiting the teaching net at all), Nolfi and Parisi allowed the standard net of a 200th generation organism to control actions using weights frozen at birth. As expected the net was a failure and clearly encoded no useful solution at birth. It does not follow, however, that the initial weights play no special role. This was nicely demonstrated by a further experiment in which the weights in the standard net were *randomized* at birth and the teach net allowed to train it as before. Under these conditions, the organism turns out to be a total failure: the randomization of the standard weights at birth destroys the ability of the overall organism (standard net/teaching net pairing) to learn to approach food. The reason is that:

the standard weights are not selected for directly incorporating good eating behaviours ... but they are accurately selected for their ability to let such a behaviour emerge by life learning. (1991, p. 10)

The initial weights of the standard network matter insofar as first, they have been selected so as to encode an initial position in weight space which avoids local minima during gradient descent learning; and second, they have been *co-selected* alongside the weights in a specific teaching network, i.e. there is potential for the harmonized evolution of specific teaching net/standard net pairings. Under such conditions of co-evolution, a given teach net may learn to give training inputs geared to the specific initial position in weight space occupied by its associated standard net. Such an exploitation of co-evolutionary possibilities would help explain the discrepancy between the results achieved by a teach net alone (when allowed to control movements) and those achieved by a teach net/standard net pairing. The necessary knowledge may be distributed in partial and non-intuitive ways between the two, and some of the teaching outputs may be geared not to coding for optimal immediate behaviour but to the task of pushing a specific point in weight space (the point which describes the initial weight-complex of the standard net) as fast as possible towards a global solution to the ingestion problem. In these ways the initial weights on the standard net may encode no directly useful knowledge about the domain while nonetheless playing a vital role in conferring on the overall system an ability to learn about that specific domain. In sum, the two sub-nets have co-evolved so as to conjointly encode a solution to the one step removed problem of how to learn about that specific domain given ecologically realistic inputs.

Evolutionary pressure acting not on individual networks but on complex networks of networks may thus lead to the development of a body of partial representations (Arbib 1993) which interact, without central executive control, so as to allow the system to learn to solve specific kinds of problem. To see just how

elusive the contents of such partial representations may become, let us consider one final twist to the Nolfi and Parisi investigation.

In a further experiment, Nolfi and Parisi allowed individual (lifetime) learning to occur *symmetrically*: that is, both the standard net *and* the teaching net were allowed to learn from each other during the organism's lifetime. In the previous simulations, recall, the teaching net was subject only to evolutionarily determined weight change. Its behaviour was therefore static within the organism's lifetime in that a given sensory input would always cause the same training signal to be produced no matter when the input was received. But as we saw earlier it is often beneficial (cf. Elman's (1991) work on the "expanding memory window" described in §4 above) for a network to receive different *kinds* of training at different temporal stages of learning. The symmetrical teaching simulation allows us to address such complexities using a population of organisms in which each sub-net passes target outputs to the other and an individual learning algorithm (back propagation) is allowed to amend the weights in each. The "teacher" net is now a kind of student too and can be led to change the training output it will produce (for a given input) as a result of weight changes induced by the output of the other network. The output of each sub-net thus contributes to changes in the weights of the other as the lifetime progresses. The possibility of complex *temporal* harmonizations of activity is thus now opened up.

The eventual performance of the symmetrical teaching net was perhaps disappointing. It did not exceed (indeed, did not even quite match) that of its predecessor. What is of interest, however, is the fact that in the new simulation the initial knowledge built in by evolution was even more arcane and diffuse. Whereas the previous teaching net clearly began life encoding a fair solution to the ingestion problem (albeit one ultimately surpassed by its own student standard net), in the symmetrical teaching case neither sub-net, when tested at birth, encoded anything approaching a useful solution. What has now evolved is instead an even more subtle kind of knowledge: knowledge about how to co-operate so as to learn, and about how to co-operate so as to learn to teach! Neither net is now clearly marked as student or teacher. But the two nets, in the context of an ecologically realistic input environment, constitute a delicately harmonized system selected to display the type and sequence of learning necessary to yield a fit mature organism.

The space of possible ways in which knowledge might be innately specified is thus very large and includes some rather subtle cases. These cases often exploit an inviting gap between raw incoming data (gross input) and the training data later seen by a downstream network engaged in some form of connectionist learning (effective input). Between these two, evolution may insert many kinds of transformation factor (see Clark (forthcoming a). The teach net in Nolfi and Parisi's first simulation is one such factor. The 3-blob filter in the Karmiloff-Smith/Johnson and Morton example is another. In exploiting such *transformation factors*, we need not (and typically do not) return to a position in which the actual environmental inputs are mere triggers for full, innate knowledge-schemes.

Instead, we confront a continuum of possible degrees of innateness corresponding to the extent to which a given transformation factor moulds the training in a certain direction. To compound such effects, the initial weights of the target (learning) network may (as in the case of the standard net in the Nolfi and Parisi simulation) have been selected so as to facilitate the acquisition of a specific type of knowledge. Further, such weights may have been selected so as to facilitate the acquisition of that knowledge *given* a transformation function which is itself subject to change as a result of feedback during the organism's individual lifetime (as in the symmetrical teaching case). And finally, transformation functions may be delicately harmonized (courtesy of co-evolution) with the initial locations of downstream networks on specific error surfaces. Nor is the notion of a transformation function limited to the particular exemplars of auto-teaching and input filtering with which we have been concerned. It includes any case in which the training input to one net is the output of another rather than direct environmental stimulation. It thus covers all cases in which learning occurs in the neurologically realistic context of signals passing through a network of networks. In pursuing the incarnation of innate knowledge in such systems we continue (*pace* Fodor) to depict the mind as fundamentally a connectionist-style learning engine. We do not seed it with any set of classical representational atoms. Nonetheless, we do depict it as a highly structured system (a co-evolved network of networks) bearing significant innate biases, and delicately coupled to the environment in which learning will take place.

5. Conclusions: the opacity of innate content

Minimal rationalism presents a peculiarly *opaque* kind of nativist picture. It is a picture in which evolution manipulates the internal resources used to encode knowledge. Yet the *content* of such native endowments is often not easily specifiable. What does a minimally favourable location on an error surface represent? What is represented in the initial weights of an evolved teaching network à la Nolfi and Parisi? The only case where we seem to have a grip on the actual *contents* involved is the 3-blob detector. This is, I think, revealing.

The reason we are able to subsume the 3-blob case under a reasonably familiar kind of content-specification is that it involves an externally specifiable content. In this case (but not the others) we can specify the content by reference to what, in the external world, it is *about*. What the other minimal rationalist options show us, however, is that very often the informational benefits of an innate endowment may be much more inward looking. They have to do with what some parts of the brain communicate to other parts of the brain (as in the auto-teaching case) or with the representational significance of the internal dynamics associated with a particular type of learning algorithm (as in the "location-on-an error surface" case). In these cases, our usual mode of content-ascription seems bound to break down. There is nothing remotely familiar for these states to be *about*.

States of the external world still enter indirectly into such stories. In speaking of an error surface we are speaking of a construct *itself* dependent on a conception of what is to count as success for the network. Our understanding of such success will itself plausibly involve reference to behaviours whose specification (e.g. "good eating behaviour") builds in reference to familiar states of affairs. But this kind of indirect involvement does not affect our main point, which is that the initial state of knowledge of a network (as determined by its *initial* weights and structure) often resists informative propositional specification while nonetheless encoding significant knowledge. For suppose all we can immediately say of some network *A* is that *A* passes training data to another net *B* in a way which is delicately geared to *B*'s initial location on an error surface. In that case the fact that the *target* location on that error surface (the place the net *should* occupy, after training) encodes a body of knowledge which will then succumb to more familiar, propositional, world-referring content-descriptions goes no way at all towards informatively specifying what is initially known by either net. Where such initial states are concerned, the process of content-ascription by correlation with real-world states simply fails to get a grip.

One option is to conclude that such initial states are *not* representational. But this is perverse. The evolutionary benefits of the innate endowments in question are clearly informational, and amount, as we remarked, to the specification of problem specific induction heuristics. All that is special about these heuristics is that they resist propositional specification.

A better option, I think, is to allow that such endowments are genuinely representational but to accept that their contents need not be expressible using the familiar resources of our public language. Such endowments do embody a kind of wisdom or knowledge, but *not* a kind which yields to the expressive resources of daily language.

The first moral, then, is that the investigation of the nature of innate knowledge should not be tied to any folk-vocabulary oriented conception of the content of such knowledge. Rather, innate knowledge may concern facts whose best expression is geometrical (as in the weight space examples) or in some other way alien. The contents of such endowments are not always to be given by familiar world-referring propositional constructions.

The second moral, already touched on earlier, is that even the intuitive division between innate representational endowments and innate structural facts is likely to be unproductive here. As we saw, the manipulation of intuitively structural elements is often equivalent to the manipulation of intuitively representational ones. Evolution is not likely to care much about which route it uses. Moreover, the fact that certain structural pre-settings (e.g. providing four layers of units in a given sub-net) do not yield benefits immediately describable in familiar representational terms cannot now be relied on to distinguish the two cases. In these circumstances, it seems best to allow that the understanding of structure, representation and learning go hand in hand. Any attempted divorce between representational and structural issues will only obscure the delicate interplay between architecture

and weights upon which much successful learning depends. In addition, unlike "maximal" rationalists such as Fodor, we cannot afford to marginalize in any way the role of the environment in presenting a rich inductive basis to the evolved organism. A "lazy" evolution will have fixed on minimal innate endowments which make the most of whatever information is there for the taking.

A final disclaimer. In arguing for a partially non-propositional (geometric, mathematical) specification of some of our innate representational repertoire I do not mean to endorse any form of eliminativism with respect to propositional content-specification schemes. Unlike e.g. P. M. Churchland (1989), I believe that a great deal of our knowledge (and the knowledge of artificial neural nets) can be usefully specified propositionally. It is not false to say that NETtalk knows something about phonemes, or that a face-recognition net knows that such-and-such a face is associated with a particular name. (At least, it is not false because of the non-classical mode of internal representation!) The fact that a particular form of internal representation is *itself* non-propositional (or non-sentential) does not show that it does not encode contents *apt for report* using propositional resources (see Clark (forthcoming b)). In some cases, however, the representational state of a non-sentential encoding device may indeed resist even propositional specification. On a minimal rationalist model, much of what we innately know will be like this: it will be knowledge about the shape of error surfaces, or knowledge about how best to filter input signals downstream, or about how to actively transform environmental inputs into useful teaching signals. In all these cases, the knowledge concerned will resist informative specification in familiar terms. But this need not surprise us. What evolution "told" the brain to encode as an aid to learning need have little in common with the eventual product of that learning: knowledge of others, of ourselves and of the external world.

To end on a traditional note, it may be worth reflecting that the story I have told amounts to this: that the brain's innate endowment may be best conceived as involving, at times, a kind of "knowing how" and not a "knowing that" (Ryle 1949). Even this "knowing how" is elusive, for we cannot specify what it concerns by reference to some external event (compare knowing how to juggle). Instead it is a know-how appropriate to the brain's own special problem: how to get the most out of the barrage of data which assail the senses, given the operation of a certain class of (gradient descent) learning algorithms. If such know-how looks alien to us, it is because *we* merely reap the rewards of our *brain's* success.

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