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Research Article

Weak Solutions of a Coupled System of Urysohn-Stieltjes Functional (Delayed) Integral Equations

A. M. A. El-Sayed 10 and M. M. A. Al-Fadel²

¹Faculty of Science, Alexandria University, Alexandria, Egypt

Correspondence should be addressed to A. M. A. El-Sayed; amasayed@gmail.com

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We study the existence of weak solutions for the coupled system of functional integral equations of Urysohn-Stieltjes type in the reflexive Banach space *E*. As an application, the coupled system of Hammerstien-Stieltjes functional integral equations is also studied.

1. Introduction and Preliminaries

Consider the Urysohn-Stieltjes integral equation:

$$x(t) = p(t) + \int_0^1 f(t, s, x(s)) d_s g(t, s), \quad t \in I = [0, 1], \quad (1)$$

where $g: I \times I \to R$ is nondecreasing in the second argument (see [1]) and the symbol d_s indicates the integration with respect to s. Equations of type (1) and some of their generalizations were considered in the paper (see [2]). We remark here that when E=R, these types of equations have been studied by Banaś (see [1–5]) and also by some other authors, for example (see [6–10] and for coupled systems [11]). For the solutions in a reflexive Banach space (see [12, 13]).

In this paper, let $\psi_i(t) \le t$ be continuous functions on [0, 1]. We generalize these results to study the existence of weak solutions $(x, y) \in C[I, E] \times C[I, E]$ for the coupled system of Urysohn-Stieltjes functional (delayed) integral equations:

$$x(t) = a_1(t) + \int_0^1 f_1(t, s, y(\psi_1(s))) d_s g_1(t, s), \quad t \in I,$$

$$y(t) = a_2(t) + \int_0^1 f_2(t, s, x(\psi_2(s))) d_s g_2(t, s), \quad t \in I,$$
(2)

in the reflexive Banach space E under the weak-weak continuity assumption imposed on $f_i: I \times I \times E \rightarrow E, i = 1, 2$.

As an application, we study the existence of weak solutions $x, y \in C[I, E]$ for the coupled system of Hammerstien-Stieltjes functional integral equations:

$$x(t) = a_1(t) + \int_0^1 k_1(t,s)h_1(s,y(\psi_1(s)))d_sg_1(t,s), \quad t \in I,$$

$$y(t) = a_2(t) + \int_0^1 k_2(t, s) h_2(s, x(\psi_2(s))) d_s g_2(t, s), \quad t \in I.$$
 (3)

For the definition, background, and properties of the Stieltjes integral, we refer to Banaś [1]. However, the coupled system of integral equations has been studied, recently, by some authors (see [14, 15]).

Throughout this paper, otherwise stated, E denotes a reflexive Banach space with norm $\|\cdot\|$ and dual E^* . Denote by C[I, E] the Banach space of strongly continuous functions $x: I \to E$ with sup-norm.

Let $X = C[I, E] \times C[I, E] = \{u(t) = (x(t), y(t)): x \in C[I, E], y \in C[I, E], t \in I\}$ be a Banach space with the norm defined as

$$\|(x,y)\|_X = \|x\|_{C[I,E]} + \|y\|_{C[I,E]}, \quad \forall (x,y) \in X. \tag{4}$$

²Faculty of Science, Omar Al-Mukhtar University, Al Bayda, Libya

Now, we shall present some auxiliary results that will be needed in this work. Let E be a Banach space (need not be reflexive) and let $x : [a, b] \rightarrow E$; then

- (1) x(.) is said to be weakly continuous (measurable) on [a,b] if for every $\phi \in E^*$, $\phi(x(.))$ is continuous (measurable) on [a,b].
- (2) A function h : E → E is said to be weakly sequentially continuous if h maps weakly convergent sequences in E to weakly convergent sequences in E.

If x is weakly continuous on I, then x is strongly measurable and hence weakly measurable (see [16, 17]). It is evident that in reflexive Banach spaces, if x is weakly continuous function on [a, b], then x is weakly Riemann integrable (see [17]). Since the space of all weakly Riemann-Stieltjes integrable functions is not complete, we will restrict our attention to the existence of weak solutions of the coupled system (2) in the space $C[I, E] \times C[I, E]$.

Definition 1. Let $f: I \times E \to E$. Then f(t, u) is said to be weakly-weakly continuous at (t_0, u_0) ; if given $\epsilon > 0$, $\phi \in E^*$; there exists $\delta > 0$ and a weakly open set U containing u_0 such that

$$|\phi(f(t,u) - f(t_0, u_0))| < \epsilon, \tag{5}$$

whenever

$$\begin{aligned} |t-t_0| &< \delta, \\ u &\in U. \end{aligned} \tag{6}$$

Now, we have the following fixed point theorem, due to O'Regan, in the Banach space (see [18]).

Theorem 1. Let E be a Banach space, let Q be a nonempty, bounded, closed, and convex subset of C[I, E], and let $F: Q \rightarrow Q$ be weakly sequentially continuous and assume that FQ(t) is relatively weakly compact in E for each $t \in I$. Then F has a fixed point in set Q.

Recall [19] that a subset of a reflexive Banach space is weakly compact if and only if it is closed in the weak topology and bounded in the norm topology. Thus, putting in mind that TQ(t) is a bounded subset of E, then the condition TQ(t) is weakly relatively compact and is automatically satisfied. Accordingly, we immediately have the following theorem.

Theorem 2. Let E be a reflexive Banach space with Q a nonempty, closed, convex, and equicontinuous subset of C[I, E]. Assume that $T: Q \rightarrow Q$ is weakly sequentially continuous. Then T has a fixed point in Q.

Proposition 1. In the reflexive Banach space, the subset is weakly relatively compact if and only if it is bounded in the norm topology.

Proposition 2. Let E be a normed space with $y \in E$ and $y \neq 0$. Then there exists a $\varphi \in E^*$ with $\|\varphi\| = 1$ and $\|y\| = \varphi(y)$.

2. Main Results

In this section, we present our main result by proving the existence of weak solutions for the coupled system of Urysohn-Stieltjes integral equation (2) in the reflexive Banach space. Let us first state the following assumptions:

Assumption 1. $a_i \in C[I, E], i = 1, 2$.

Assumption 2. $\psi_i: I \to I$ is a continuous function such that $\psi_i(t) \le t$.

Assumption 3. $f_i: I \times I \times E \rightarrow E, i = 1, 2$ satisfy the following conditions:

- (1) $f_i(\ldots, s, x(\psi_i(s)))$ are continuous functions on I for every $x \in E$.
- (2) $f_i(t,...)$ are weakly-weakly continuous functions, $\forall t \in I$
- (3) There exist two continuous functions $m_i(t), m_i$: $I \times I \to I$ and two positive constants b_i , such that $||f_i(t,s,x)|| \le m_i(t,s) + b_i||x||, i = 1, 2.$

Assumption 4. The functions $t \to g_i(t, 1)$ and $t \to g_i(t, 0)$ are continuous on I.

Assumption 5. For all $t_1, t_2 \in I$ such that $t_1 < t_2$, the functions $s \to g_i(t_2, s) - g_i(t_1, s)$ are nondecreasing on I.

Assumption 6. $g_i(0, s) = 0$, for any $s \in I$.

Remark 1. Observe that Assumptions 5 and 6 imply that the function $s \to g(t,s)$ is nondecreasing on the interval I, for any fixed $t \in I$ (Remark 1 in [5]). Indeed, putting $t_2 = t$, $t_1 = 0$ in Assumption 5 and keeping in mind Assumption 6, we obtain the desired conclusion. From this observation, it follows immediately that, for every $t \in I$, the function $s \to g(t,s)$ is of bounded variation on I.

Definition 2. By a weak solution for the coupled system (2), we mean the pair of functions $(x, y) \in C[I, E] \times C[I, E]$ such that

$$\begin{split} \varphi(x(t)) &= \varphi(a_1(t)) + \int_0^1 \varphi(f_1(t,s,y(\psi_1(s)))) d_s g_1(t,s), \quad t \in I, \\ \varphi(y(t)) &= \varphi(a_2(t)) + \int_0^1 \varphi(f_2(t,s,x(\psi_2(s)))) d_s g_2(t,s), \quad t \in I, \end{split}$$

for all $\varphi \in E^*$.

Now, let

$$\mu = \max \left\{ \sup_{t} |g_{i}(t, 1)| + \sup_{t} |g_{i}(t, 0)|, \quad t \in I \right\}, i = 1, 2,$$

$$M = \max \left\{ m_{i}(t, s) : t, \quad s \in I \right\}.$$
(8)

Then we have the following theorem.

Theorem 3. Under the Assumptions 1–6, the coupled system of Urysohn-Stieltjes integral equation (2) has at least one weak solution $(x, y) \in C[I, E] \times C[I, E]$.

Proof 1. Define an operator A by

$$A(x, y) = (A_1 y, A_2 y),$$
 (9)

where

$$\begin{split} A_1y(t) &= a_1(t) + \int_0^1 & f_1(t,s,y(\psi_1(s))) d_s g_1(t,s), \quad t \in I, \\ A_2x(t) &= a_2(t) + \int_0^1 & f_2(t,s,x(\psi_2(s))) d_s g_2(t,s), \quad t \in I. \end{split} \label{eq:A1y}$$

For every $x_i \in C[I, E]$, $f_i(\ldots, s, x(\psi_i(s)))$ is continuous on I, and $f_i(t, \ldots, x(\psi_i(.)))$ are weakly continuous on I; then $\varphi(f_i(t, \ldots, x(\psi_i(.))))$ are continuous for every $\varphi \in E^*$. Hence, in view of bounded variational of g_i it follows, $f_i(t, s, x(\psi_i(s)))$ is weakly Riemann-Stieltjes integrable on I with respect to $s \to g_i(t, s)$. Thus, A_i make sense.

Now, we can prove that $A_1:C[I,E]\to C[I,E]$ and for $\epsilon>0$, $t_1,t_2\in I$, $t_1< t_2$, and $t_2-t_1<\epsilon$ (without loss of generality, assume that $A_1y(t_2)-A_1y(t_1)\neq 0$), and there exists $\varphi\in E^*$, such that

$$\begin{split} &\|A_{1}y(t_{2})-A_{1}y(t_{1})\|\\ &\leq |\varphi(a_{1}(t_{2})-a_{1}(t_{1}))|+\left|\int_{0}^{1}\varphi(f_{1}(t_{2},s,y(\psi_{1}(s))))d_{s}g_{1}(t_{2},s)\right|\\ &-\int_{0}^{1}\varphi(f_{1}(t_{1},s,y(\psi_{1}(s))))d_{s}g_{1}(t_{1},s)\Big|\\ &\leq \|a_{1}(t_{2})-a_{1}(t_{1})\|+\left|\int_{0}^{1}\varphi(f_{1}(t_{2},s,y(\psi_{1}(s))))d_{s}g_{1}(t_{2},s)\right|\\ &-\int_{0}^{1}\varphi(f_{1}(t_{1},s,y(\psi_{1}(s))))d_{s}g_{1}(t_{2},s)\Big|\\ &+\left|\int_{0}^{1}\varphi(f_{1}(t_{1},s,y(\psi_{1}(s))))d_{s}g_{1}(t_{2},s)\right|\\ &-\int_{0}^{1}\varphi(f_{1}(t_{1},s,y(\psi_{1}(s))))d_{s}g_{1}(t_{1},s)\Big| \end{split}$$

$$\leq \|a_{1}(t_{2}) - a_{1}(t_{1})\| + \int_{0}^{1} |\varphi(f_{1}(t_{2}, s, y(\psi_{1}(s)))) \\ - f_{1}(t_{1}, s, y(\psi_{1}(s))))|d_{s}\left(\bigvee_{z=0}^{s} g_{1}(t_{2}, z)\right) \\ + \int_{0}^{1} |\varphi(f_{1}(t_{1}, s, y(\psi_{1}(s))))|d_{s}\left(\bigvee_{z=0}^{s} [g_{1}(t_{2}, z) - g_{1}(t_{1}, z)]\right) \\ \leq \|a_{1}(t_{2}) - a_{1}(t_{1})\| + \|f_{1}(t_{2}, s, y) - f_{1}(t_{1}, s, y)\| \int_{0}^{1} d_{s}g_{1}(t_{2}, s) \\ + \int_{0}^{1} \|f_{1}(t_{1}, s, y)\| d_{s}[g_{1}(t_{2}, s) - g_{1}(t_{1}, s)] \\ \leq \|a_{1}(t_{2}) - a_{1}(t_{1})\| + \|f_{1}(t_{2}, s, y) - f_{1}(t_{1}, s, y)\| \\ \cdot [g_{1}(t_{2}, 1) - g_{1}(t_{2}, 0)] + \int_{0}^{1} m_{1}(t, s) d_{s}[g_{1}(t_{2}, s) - g_{1}(t_{1}, s)] \\ \leq \|a_{1}(t_{2}) - a_{1}(t_{1})\| + \|f_{1}(t_{2}, s, y) - f_{1}(t_{1}, s, y)\| [g_{1}(t_{2}, 1) \\ - g_{1}(t_{2}, 0)] + M \int_{0}^{1} d_{s}[g(t_{2}, s) - g(t_{1}, s)] \\ \leq \|a_{1}(t_{2}) - a_{1}(t_{1})\| + \|f_{1}(t_{2}, s, y) - f_{1}(t_{1}, s, y)\| [g_{1}(t_{2}, 1) \\ - g_{1}(t_{2}, 0)] + (M + b_{1}r_{1}) \\ \cdot [g(t_{2}, 1) - g(t_{1}, 1)) - (g(t_{2}, 0) - g(t_{1}, 0))] \\ \leq \|a_{1}(t_{2}) - a_{1}(t_{1})\| + \|f_{1}(t_{2}, s, y) - f_{1}(t_{1}, s, y)\| \\ \cdot [g_{1}(t_{2}, 1) - g_{1}(t_{2}, 0)] + (M + b_{1}r_{1})[|g_{1}(t_{2}, 1) - g_{1}(t_{1}, 1)| \\ + |g_{1}(t_{2}, 0) - g_{1}(t_{1}, 0)|].$$

Hence,

$$\begin{split} \|A_{1}y(t_{2}) - A_{1}y(t_{1})\| &\leq \|a_{1}(t_{2}) - a_{1}(t_{1})\| + \|f_{1}(t_{2}, s, y) \\ &- f_{1}(t_{1}, s, y)\|[g_{1}(t_{2}, 1) - g_{1}(t_{2}, 0)] \\ &+ (M + b_{1}r_{1})[|g_{1}(t_{2}, 1) - g_{1}(t_{1}, 1)| \\ &+ |g_{1}(t_{2}, 0) - g_{1}(t_{1}, 0)|]. \end{split}$$

Similarly, we can show that

$$\begin{split} \|A_2x(t_2) - A_2x(t_1)\| &\leq \|a_2(t_2) - a_2(t_1)\| + \|f_2(t_2, s, y) \\ &- f_2(t_1, s, y)\|[g_2(t_2, 1) - g_2(t_2, 0)] \\ &+ (M + b_2r_2)[|g_2(t_2, 1) - g_2(t_1, 1)| \\ &+ |g_2(t_2, 0) - g_2(t_1, 0)|]. \end{split}$$

Now,

$$\begin{split} A(x,y)(t_2) - A(x,y)(t_1) &= (A_1y(t_2),A_2x(t_2)) - (A_1y(t_1),A_2x(t_1)) \\ &= ((A_1y(t_2) - A_1y(t_1)),(A_2x(t_2) - A_2x(t_1))), \end{split}$$

and

$$\begin{split} &\|A(x,y)(t_{2})-A(x,y)(t_{1})\|\\ &\leq \|A_{1}y(t_{2})-A_{1}y(t_{1})\|+\|A_{2}x(t_{2})-A_{2}x(t_{1})\|\\ &\leq \|a_{1}(t_{2})-a_{1}(t_{1})\|+\|f_{1}(t_{2},s,y)-f_{1}(t_{1},s,y)\|\\ &\cdot [g_{1}(t_{2},1)-g_{1}(t_{2},0)]+(M+b_{1}r_{1})\\ &\cdot [|g_{1}(t_{2},1)-g_{1}(t_{1},1)|+|g_{1}(t_{2},0)-g_{1}(t_{1},0)|]\\ &+\|a_{2}(t_{2})-a_{2}(t_{1})\|+\|f_{2}(t_{2},s,y)-f_{2}(t_{1},s,y)\|\\ &\cdot [g_{2}(t_{2},1)-g_{2}(t_{2},0)]+(M+b_{2}r_{2})\\ &\cdot [|g_{2}(t_{2},1)-g_{2}(t_{1},1)|+|g_{2}(t_{2},0)-g_{2}(t_{1},0)|]. \end{split}$$

Then from the continuity of the functions, g_i is required in Assumption 4; we deduce that A maps X into X.

Define the sets Q_1 and Q_2 by

$$Q_1 = \{ y \in C[I, E] \colon ||y|| \le r_1 \}, \quad r_1 = \frac{||a_1|| + M\mu}{1 - b_1 \mu}, \tag{16}$$

and

$$Q_2 = \left\{ x \in C[I, E] \colon \|x\| \le r_2 \right\}, \quad r_2 = \frac{\|a_2\| + M\mu}{1 - b_2\mu}. \tag{17}$$

Now, define the closed, convex, bounded, equicontinuous set Q by

$$\begin{split} Q &= \big\{ u = (x,y) \in X : \|u\| \leq r_1 + r_2, \|u(t_2) - u(t_1)\| \leq \|a_1(t_2) \\ &- a_1(t_1)\| + \|f_1(t_2,s,y) - f_1(t_1,s,y)\| [g_1(t_2,1) \\ &- g_1(t_2,0)] + (M+b_1r_1)[|g_1(t_2,1) - g_1(t_1,1)| \\ &+ |g_1(t_2,0) - g_1(t_1,0)|] + \|a_2(t_2) - a_2(t_1)\| \\ &+ \|f_2(t_2,s,y) - f_2(t_1,s,y)\| [g_2(t_2,1) - g_2(t_2,0)] \\ &+ (M+b_2r_2)[|g_2(t_2,1) - g_2(t_1,1)| + |g_2(t_2,0) - g_2(t_1,0)|] \big\}. \end{split}$$

Now, let $y \in Q_1$ and $x \in Q_2$; without loss of generality, we may assume $A_1y \neq 0$, $A_2x(t) \neq 0$, $t \in I$. By Proposition 2, we have

$$\begin{split} \|A_1y(t)\| &= \varphi(A_1y(t)) \leq |\varphi(a_1(t))| \\ &+ \left| \varphi \left(\int_0^1 f_1(t,s,y(\psi_1(s))) d_s g_1(t,s) \right) \right| \\ &\leq \|a_1\| + \int_0^1 |\varphi(f_1(t,s,y(\psi_1(s))))| d_s \left(\bigvee_{z=0}^s g_1(t,z) \right) \\ &\leq \|a_1\| + \int_0^1 \|f_1(t,s,y(\psi_1(s)))\| d_s \left(\bigvee_{z=0}^s g_1(t,z) \right) \\ &\leq \|a_1\| + \int_0^1 m_1(t,s) d_s g_1(t,s) + \int_0^1 b_1 \|y\| d_s g_1(t,s) \\ &\leq \|a_1\| + M \int_0^1 d_s g_1(t,s) + b_1 r_1 \int_0^1 d_s g_1(t,s) \end{split}$$

$$\leq \|a_1\| + M[g_1(t,1) - g_1(t,0)]$$

$$+ b_1 r_1[g_1(t,1) - g_1(t,0)]$$

$$\leq \|a_1\| + (M + b_1 r_1) \left[\sup_{t \in I} |g_1(t,1)| + \sup_{t \in I} |g_1(t,0)| \right]$$

$$\leq \|a_1\| + (M + b_1 r_1) \mu.$$

$$(19)$$

Then

$$||A_1 y(t)|| \le ||a_1|| + (M + b_1 r_1)\mu = r_1.$$
 (20)

Similarly, we can prove that

$$||A_2x(t)|| \le ||a_2|| + (M + b_2r_2)\mu = r_2.$$
 (21)

Therefore, for any $u \in Q$,

$$\begin{aligned} \|Au(t)\| &= \|A(x,y)(t)\| = \|(A_1y(t),A_2x(t))\| \\ &\leq \|A_1y(t)\| + \|A_2x(t)\| \\ &\leq \|a_1\| + (M+b_1r_1)\mu + \|a_2\| + (M+b_2r_2)\mu \\ &= r_1 + r_2, \end{aligned}$$
 (22)

that is, $\forall u \in Q \Rightarrow Au \in Q \Rightarrow AQ \subset Q$. Thus, $A: Q \rightarrow Q$.

Note that Q is a nonempty, uniformly bounded, and strongly equicontinuous subset of X, by the uniform boundedness of AQ; according to Proposition 1, AQ is relatively weakly compact.

It remains to prove that A is weakly sequentially continuous.

Let $\{y_n(t)\}$ and $\{x_n(t)\}$ be sequences in C[I,E] weakly convergent to y(t) and x(t), respectively $(\forall t \in I)$, since $f_1(t,s,\dots)$ and $f_2(t,s,\dots)$ are weakly continuous. Then $f_1(t,s,y_n(\psi_1(s)))$ and $f_2(t,s,x_n(\psi_2(s)))$ converge weakly to $f_1(t,s,y(\psi_1(s)))$ and $f_2(t,s,x(\psi_2(s)))$, respectively. Furthermore, $(\forall \varphi \in E^*)\varphi(f_1(t,s,y_n(\psi_1(s))))$ and $\varphi(f_2(t,s,x_n(\psi_2(s))))$ converge strongly to $\varphi(f_1(t,s,y(\psi_1(s))))$ and $\varphi(f_2(t,s,x(\psi_2(s))))$, respectively. Applying the Lebesgue-dominated convergence theorem, then we get

$$\begin{split} \varphi\bigg(\int_0^1 &f_1(t,s,y_n(\psi_1(s)))d_sg_1(t,s)\bigg)\\ &=\int_0^1 &\varphi(f_1(t,s,y_n(\psi_1(s))))d_sg_1(t,s) \longrightarrow \int_0^1 &\varphi(f_1(t,s,y(\psi_1(s))))d_sg_1(t,s),\\ &\forall \varphi \in E^*, t \in I, \end{split}$$

and

$$\begin{split} \varphi\bigg(\int_0^1 & f_2(t,s,x_n(\psi_2(s))) d_s g_2(t,s)\bigg) \\ &= \int_0^1 & \varphi(f_2(t,s,x_n(\psi_2(s)))) d_s g_2(t,s) \longrightarrow \int_0^1 & \varphi(f_2(t,s,x(\psi_2(s)))) d_s g_2(t,s), \\ & \forall \varphi \in E^*, t \in I. \end{split}$$

Thus, A is weakly sequentially continuous on Q.

Since all conditions of Theorem 1 are satisfied, then the operator A has at least one fixed point $(x, y) = u \in Q$ and the coupled system of Urysohn-Stieltjes integral equation (2) has at least one weak solution.

3. Hammerstein-Stieltjes Coupled System

This section, as an application, deals with the existence of weak continuous solution for the coupled system of Hammerstein-Stieltjes functional integral equation (3). Consider the following assumption:

Assumption 7. Let $h_i: I \times E \to E$ and $k_i: I \times I \to R_+$ assume that h_i, k_i satisfy the following assumptions:

- (1) $h_i(s, x(\psi_i(s)))$ are weakly-weakly continuous functions.
- (2) There exist continuous functions $m_i^*(t)$ and constants $b_i > 0$ such that

$$||h_i(t,x)|| \le m_i^*(t) + b_i||x||,$$
 (25)

for $t, s \in I, x \in E$. Moreover, we put $M^* = \max \{m_i^* (t): t \in I\}, M^* > 0$.

(3) $k_i(t, s)$ is a continuous function such that $K = \sup_t |k_i(t, s)|$, where K is a positive constant.

Definition 3. By a weak solution for the coupled system (3), we mean the pair of functions $(x, y) \in C[I, E] \times C[I, E]$ such that

$$\varphi(x(t)) = \varphi(a_1(t)) + \int_0^1 k_1(t, s) \varphi(h_1(s, y(\psi_1(s)))) d_s g_1(t, s), \quad t \in I,$$

$$\varphi(y(t)) = \varphi(a_2(t)) + \int_0^1 k_2(t, s) \varphi(h_2(s, x(\psi_2(s)))) d_s g_2(t, s), \quad t \in I,$$
(26)

for all $\varphi \in E^*$.

Being new for the existence of weak solutions of (3), we have the following theorem.

Theorem 4: Let Assumptions 1, 2, 4, 5, and 7 be satisfied. Then the coupled system of Hammerstien-Stieltjes functional integral equation (3) has at least one weak solution $(x, y) \in X$.

Proof 2. Let

$$f_i(t, s, x(s)) = k_i(t, s)h_i(s, x(\psi_i(s))).$$
 (27)

Then from Assumption 7, we find that the assumptions of Theorem 3 are satisfied and the result follows.

For example, consider the functions $g_i: I \times I \rightarrow R$ defined by the formula

$$g_{1}(t,s) = \begin{cases} t \ln \frac{t+s}{t}, & \text{for } t \in (0,1], s \in I, \\ 0, & \text{for } t = 0, s \in I, \end{cases}$$

$$g_{2}(t,s) = t(t+s-1), \quad t \in I.$$
(28)

It can be easily seen that the functions $g_1(t,s)$ and $g_2(t,s)$ satisfy assumptions (iv)-(vi) given in Theorem given in Theorem 3. In this case, the coupled system of Urysohn-Stieltjes integral equation (2) has the following form:

$$x(t) = a_1(t) + \int_0^1 \frac{t}{t+s} f_1(t, s, y(\psi_1(s))) ds, \quad t \in I,$$
 (29)

$$y(t) = a_2(t) + \int_0^1 t f_2(t, s, x(\psi_i(s))) ds, \quad t \in I.$$
 (30)

Therefore, the coupled system (29) has at least one weak solution $u = (x, y) \in X$, if the functions a_i , ψ_i , and f_i satisfy Assumptions 1–3.

Data Availability

There is no data availability.

Conflicts of Interest

The authors declare that there is no conflict of interest regarding the publication of this paper.

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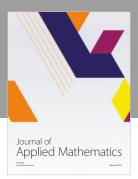
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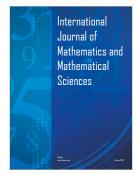
















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