

## **No Free Lunch Theorem, Inductive Skepticism, and the Optimality of Meta-Induction**

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**Abstract:** The no free lunch theorem (Wolpert 1996) is a radicalized version of Hume's induction skepticism. It asserts that relative to a uniform probability distribution over all possible worlds, all computable prediction algorithms – whether 'clever' inductive or 'stupid' guessing methods (etc.) – have the same expected predictive success. This theorem seems to be in conflict with results about meta-induction (Schurz 2008). According to these results, certain meta-inductive prediction strategies may dominate other (non-meta-inductive) methods in their predictive success (in the long run). In this paper this conflict is analyzed and dissolved, by means of probabilistic analysis and computer simulation.

### **1. The Optimality of Meta-Induction: A Solution to the Problem of Induction?**

In Schurz (2008) a new account to the problem of induction has been developed that is based on the optimality of meta-induction. The account agrees with Hume's skeptical insight that it is impossible to demonstrate a priori that induction is *reliable* in the sense that it is predictively more successful than random guessing. Such a demonstration is impossible without assuming that the actual world possesses a certain amount of regularity. Reichenbach (1949, §91) argued that it is at least possible to demonstrate a priori that induction

is *optimal*, i.e., is the best what we can do for the purpose of predictive success. Results in formal learning show, however, that it is not possible to demonstrate optimality at the level of *object-induction*, that is, of induction applied to the task of predicting events in arbitrary possible worlds (cf. Skyrms 1975, ch. III.4). In contrast, what the account of *meta-induction* attempts to show is that induction is optimal if it is applied at the meta-level of competing prediction methods. The meta-inductive strategy tracks the success rate of all prediction methods whose predictions are *accessible* and predicts an optimal weighted average of the predictions of those methods that were most successful so far. Based on results in mathematical learning theory (Cesa-Bianchi 2006), Schurz (2008) proved that there exists a particular weighting method, called *attractivity-weighting*, which grants the meta-inductivist a predictive success rate that is in the long run at least as high as that of every other prediction method that is accessible to the meta-inductivist, even if their success rates are permanently changing in an irregular way. Since the restriction to accessible methods is crucial for the optimality theorem, Schurz and Thorn (2016) call this kind of optimality *access-optimality*. Remarkably, the access-optimality of meta-induction holds in *all* possible worlds, even in 'chaotic' ones in which event frequencies do not converge against limits or in 'paranormal' worlds which host clairvoyants.

Technically the account of meta-induction is based on the notion of a prediction game:

**Definition 1.** A *prediction game* is a pair  $((e), \Pi)$  consisting of:

(1.) An infinite sequence  $(e) := (e_1, e_2, \dots)$  of events  $e_n$ , coded by real numbers between 0 and 1, possibly rounded according to a finite accuracy. For example,  $(e)$  may be a sequence

of daily weather conditions, football game results, or stock values. In what follows  $\text{Val} \subseteq [0,1]$  denotes the value space of possible events  $e_n \in \text{Val}$ . Each time  $n$  corresponds to one round of the game.

(2.) A finite set of prediction methods or 'players'  $\Pi = \{P_1, \dots, P_m, \text{MI}\}$  (in what follows we identify 'methods' with 'players'). In each round it is the task of each player to predict the next event of the event sequence. "MI" signifies the meta-inductivist and the other players are the 'non-MI-players' or 'candidate methods'. They may be real-life experts, virtual players implemented by computational algorithms, or even 'clairvoyants' who can see the future in 'para-normal' possible worlds. It is assumed that the predictions of the non-MI players are accessible to the meta-inductivist. Moreover, they are elements of  $\text{Val} \subseteq [0,1]$ .

The *predictive success rate* of a method  $P$  is defined by means of the following chain of definitions:

- $\text{pred}_n(P)$  is the prediction of *player*  $P$  for time  $n$  delivered *at* time  $n-1$ ,
- the deviation of the prediction  $\text{pred}_n$  from the event  $e_n$  is measured by a normalized loss function,  $\text{loss}(\text{pred}_n, e_n) \in [0,1]$ ,
- $\text{score}(\text{pred}_n, e_n) \stackrel{\text{def}}{=} 1 - \text{loss}(\text{pred}_n, e_n)$  is the *score* obtained by prediction  $\text{pred}_n$  of event  $e_n$ ,
- $\text{abs}_n(P) \stackrel{\text{def}}{=} \sum_{1 \leq i \leq n} \text{score}(\text{pred}_i(P), e_i)$  is the *absolute* success achieved by player  $P$  until time  $n$ , and
- $\text{suc}_n(P) \stackrel{\text{def}}{=} \text{abs}_n(P)/n$  is the *success rate* of player  $P$  at time  $n$ .

The *natural* loss-function is defined as  $|\text{pred}_n - e_n|$ . The optimality theorem holds below for

all *convex* loss functions, which means that the loss of a weighted average of two predictions is not greater than the weighted average of the losses of two predictions. In what follows we assume convex loss functions; they comprise a large variety of loss functions including all linear, polynomial, or exponential functions of the natural loss function.

'Possible worlds' are identified with prediction games. A special case are *binary* games whose events and predictions are elements of  $\{0,1\}$ . For binary games the natural loss function coincides with the zero-one loss:  $\text{loss}_{1-0}(\text{pred},e) = 0$  if  $\text{pred} = e$ , and otherwise  $= 1$ .

The simplest meta-inductive strategy is called "Imitate-the-best" and predicts what the presently best non-MI player predicts. It is easy to see that this meta-inductive method cannot be universally access optimal: Its success rate breaks down when it plays against non-MI methods that are *deceivers*, which means that they lower their success rate as soon as their predictions are imitated by the meta-inductivist (cf. Schurz 2008, sec. 4). A realistic example is the prediction of stock values in a 'bubble economy': Here the prediction that a given stock will yield a high rate of return leads many investors to put their money on this stock and by doing so they cause it to crash. Nevertheless there exists a meta-inductive strategy that is provably universally optimal. This strategy is called *attractivity-weighted meta-induction*, abbreviated as wMI, and is defined as follows:

**Definition 2.** The predictions of wMI (attractivity-weighted meta-induction) are defined as

$$\text{pred}_{n+1}(\text{wMI}) \stackrel{\text{def}}{=} \frac{\sum_{1 \leq i \leq m} \text{at}_n(P_i) \cdot \text{pred}_{n+1}(P_i)}{\sum_{1 \leq i \leq m} \text{at}_n(P_i)}, \text{ where}$$

–  $\text{at}_n(P_i)$  is the attractivity of a player  $P_i$  for wMI at a given time  $n$ , defined as

$at_n(P_i) =_{\text{def}} \text{suc}_n(P_i) - \text{suc}_n(\text{wMI})$ , if this expression is positive; else  $at_n(P_i) = 0$ , and

– if  $n=1$  or the denominator is zero, wMI's prediction is a random guess.

Let "maxsuc<sub>n</sub>" denote the non-MI-players' maximal success rate at time  $n$ . Then the optimality theorem for wMI (proved in Schurz 2008, sec. 7, theorem 4) asserts:

**Theorem 1.** (Universal access-optimality for wMI):

For every prediction game  $((e), \{P_1, \dots, P_m, \text{wMI}\})$  the following holds:

(1.1) (Short run:)  $(\forall n \geq 1:) \text{suc}_n(\text{wMI}) \geq \text{maxsuc}_n - \sqrt{m/n}$ .

(1.2) (Long-run:)  $\text{suc}_n(\text{wMI})$  (strictly) converges to the non-MI-players' maximal success for  $n \rightarrow \infty$ .

According to theorem (1.2) attractivity-weighted meta-induction is long-run optimal for *all* possible event sequences and sets of accessible prediction methods. The only proviso is that the set of accessible methods is finite, which is a realistic assumption for cognitively finite beings. In the short run, weighted meta-induction may suffer from a possible loss, compared to the leading player. This loss (which is also called wMI's 'regret') is caused by the fact that wMI must base her prediction of the next event on the *past* success rates of the candidate methods, and the hitherto most attractive methods may perform badly in the prediction of the *next* event. Fortunately theorem (1.1) states a worst-case upper bound for this loss, which is small if the number of competing methods,  $m$ , is small compared to the number of rounds,  $n$ , and which converges quickly to zero when  $n$  grows large.

Theorem 1 applies to prediction games with real-valued as well as binary (or discrete) events. Even if the events are binary wMI's predictions are real-valued (because proper weighted averages of 0s and 1s are real-valued). How can the optimality result of theorem 1 be transferred to binary games whose predictions must be binary? There are two methods by which this can be done:

(1.) Randomization, rwMI (cf. Cesa-Bianchi and Lugosi 2006, sec. 4.1): Here one assumes that rwMI predicts  $e_n=1$  with a probability (P) that equals the optimal real-valued prediction of wMI, i.e.,  $P(\text{pred}_n(\text{rwMI})=1) = \text{pred}_n(\text{wMI})$ . This method is not entirely general since it presupposes that the events are probabilistically independent from rwMI's choice of prediction.

(2.) Collective meta-induction, cwMI (Schurz 2008, sec. 8): Here a *collective* of meta-inductivists approximates real-valued predictions by the mean value of their binary predictions. Their mean predictive success rate approximates provably the success rate of the optimal method wMI. Assuming that the cwMIs are *cooperators* and share their success, every individual member of the collective is predictively optimal.

Theorem 1 establishes the following a priori justification of attractivity-weighted meta-induction: In all environments it is reasonable – in *addition* to searching for good object-level methods – to apply the strategy wMI, as this can only improve but not worsen one's success in the long run. Note that by itself this justification does not entail anything about the rationality of object-level induction: it may well be that we live in a world in which a method different from object-induction is predictively superior. However, it seems that the a priori justification of meta-induction give us the following a posteriori justification of

object-induction: to the extent that (a particular version of) object-induction was so far the most successful prediction strategy, it is meta-inductively reasonable to continue favoring (this particular version of) object-induction.

Theorem 1 asserts the optimality but not the dominance (in the long run) of attractivity-based meta-induction. Thus there may exist other methods, different from wMI, that are likewise long-run optimal. In fact one can prove that there are certain variants of wMI that are long-run optimal and have short-run advantages in certain and disadvantages in other environments. So wMI is cannot be universally long-run dominant. Nevertheless, the following restricted dominance result for wMI follows from theorem 1:

**Theorem 2.** (Dominance for wMI):

(2.1) wMI dominates every prediction method that is not universally long-run optimal. In other words, for every such method  $M$  there is a prediction game containing wMI and  $M$  in which wMI's long-run success rate exceeds that of  $M$ .

(2.2) Not universally long-run optimal are, for example, all *independent* non-clairvoyant methods, that is, methods that can learn only from observations of past events, but not from the predictions of other methods.

*Proof of theorem 2:* Theorem (2.1) is an immediate consequence of theorem 1 and the definition of "optimality". The proof of theorem (2.2) goes as follows: Let  $M$  be an independent method based on a function  $f$  that maps each  $n$ -tuple of past events  $(e_1, \dots, e_n) \in \text{Val}^n$

into a prediction  $\text{pred}_{n+1} \in \text{Val}$ . We define an  $M$ -adversarial event sequence  $(e')$  as follows:  $e'_1 = 0.5$ , and  $e'_{n+1} = 1$  if  $f(e'_1, \dots, e'_n) \leq 0.5$ ; else  $e'_{n+1} = 0$ . Moreover we identify the predictions of the perfect  $(e')$ -forecaster  $M'$  with the so-defined sequence, i.e.,  $\text{pred}_n(M') = e'_n$  (note that if  $f$  is computable,  $M'$  is so, too). In the prediction game  $((e'), \{M, M', \text{wMI}\})$  the success rate of  $M$  can never exceed  $1/2$ , that of  $M'$  is always 1 and that of  $\text{wMI}$  converges to 1 (by theorem 1). This proves theorem 2. Q.E.D.

Theorem 2 is crucial for the next sections in which we confront the optimality of meta-induction with the no free lunch theorem.

## 2. Radical Inductive Skepticism: The No Free Lunch Theorem

Wolpert's (in)famous no free lunch theorem (Wolpert 1996) is a radicalized version of Hume's inductive skepticism for theoretical computer science. The theorem applies to prediction methods that can be represented as computable functions from past observations to predictions, so called *learning algorithms* (thus, clairvoyance is excluded). The theorem is often expressed by the assertion that for each pair of prediction methods, the number – or in the infinite case the probability – of possible worlds (event sequences) in which the first method outperforms the second is precisely equal to the number (or probability) of worlds in which the second method outperforms the first. We call this assertion the *strong* version of Wolpert's theorem, because it presupposes a 'homogeneous' loss function:



**Theorem 3.** Strong no free lunch theorem (Wolpert 1996, 1354f, theorems 1, 3):

For every possible loss value  $c$ , the probability of worlds in a which prediction method leads to a loss of  $c$  is the same for all possible prediction methods, *provided* one assumes

- (a) a *state-uniform* prior probability distribution, that is, a uniform distribution over all possible event sequences (or *states* of the world), and
- (b) a homogeneous loss function, in the sense that for all possible loss values  $c$ , the number of possible events  $e \in \text{Val}$  for which a prediction  $\text{pred} \in \text{Val}$  leads to a loss of  $c$  is the same for all possible predictions  $\text{pred} \in \text{Val}$ .

The requirement of a homogeneous loss function very strong: It is only satisfied if events *and* predictions are binary, or more generally, if they are discrete with a zero-one loss function. Under this assumption homogeneity is obvious: If the value space has  $k$  elements, then for every  $\text{pred} \in \text{Val}$  the number of possible events  $e \in \text{Val}$  that lead to a loss of 1 is obviously  $k-1$ , and the number of events that lead to a loss of 0 is one. In contrast, in prediction games with real-valued predictions the homogeneity requirement fails. In the binary case, for example, the number of events which lead to a loss of 1 is one for the two predictions  $\text{pred} = 1$  and  $\text{pred} = 0$ , but zero for the prediction  $\text{pred} = 0.5$ .

Homogeneous loss functions are a clear restriction of the strong no free lunch theorem, since, as we have seen, real-valued predictions can be implemented even in binary games, either by randomized binary predictions or by a cooperative collective of binary forecasters. There is, however, a weak version of the no free lunch theorem (mentioned by Wolpert

1996 on p. 1354 ) which applies to real-valued predictions over binary or discrete events and assumes what we call a "weakly homogeneous" loss function:

**Theorem 4.** Weak no free lunch theorem (Wolpert 1996, 1354):

The probabilistically expected success of every possible prediction method is equal to the expected success of random guessing or of every other prediction method, provided one assumes

- (a) a *state-uniform* prior probability distribution, and
- (b) a weakly homogeneous loss function, in the sense that for every possible prediction  $\text{pred} \in \text{Val}$  the *sum* of pred's losses over all possible events  $e \in \text{Val}$  is the same ( $\forall \text{pred} \in \text{Val}: \sum_{e \in \text{Val}} \text{loss}(\text{pred}, e) = \text{a constant } c^*$ ).

For binary events with real-valued predictions and a natural loss function weak homogeneity is satisfied, since for every prediction  $\text{pred} \in [0, 1]$ ,  $\text{loss}(\text{pred}, 1) + \text{loss}(\text{pred}, 0) = 1 - \text{pred} + \text{pred} = 1$ .

For prediction games with real-valued events, most loss functions (including all convex ones) are not even weakly homogeneous. Here "free lunches" are possible in the sense that not all prediction methods have the same expected success, relative to a state-uniform probability distribution.

In this paper we focus on prediction games with discrete events and real-valued predictions, to which the weak no free lunch theorem applies. The framework in which Wolpert proves his theorems are not prediction games, but learning algorithms that map training

sets into predictions of test items. But since a prediction game can be considered as an iterated procedure of selecting a training set of  $n$  events and predicting the event at test item  $n+1$ , Wolpert's result applies straightforwardly to prediction games.

Theorem 4 asserts that *every* possible prediction method – be it an intelligent inductive one, a crazy anti-inductive one, or a stupid one that always predicts the same value – has the same expected predictive success relative to a state-uniform prior distribution. For all induction-friendly philosophical programs, including the program of meta-induction, this result seems to be devastating. How is it possible? In what follows we give a brief explanation of Wolpert's theorem in terms that are philosophically more familiar than his own "extended Bayesian framework".

Wolpert's theorem is a far-reaching generalization of a straightforward result about the prediction of binary sequences. For this application the strong no free lunch theorem amounts to the following: However a prediction function  $f$ , with  $\text{pred}_{n+1} = f((e_1, \dots, e_n)) \in \{0,1\}$ , is defined, there are as many sequences of a given length  $k > n$  extending  $(e_1, \dots, e_n)$  that verify  $f$ 's prediction  $\text{pred}_{n+1}$  as there are sequences that falsify it. Thus by attaching an equal probability to every possible sequence the expected score of each prediction function will be  $1/2$ . More generally speaking, this result is an immediate consequence of an (in)famous result in probability theory which can be found (among other authors) in Carnap (1950, 564-566) or Howson and Urbach (1996, 64-66). The result can be expressed as follows:

**Theorem 5.** (Carnap 1950, 564-566):

Let  $P$  be a state-uniform prior probability (density) distribution over (the Borel algebra over)<sup>1</sup> the set of all infinite binary sequences,  $\{0,1\}^\omega$ . Then  $P$  has the following two 'radically non-inductive' properties:

(a)  $P$  assigns the same conditional probability to each event  $e_n \in \{0,1\}$  independently of the preceding events  $(e_1, \dots, e_{n-1})$  of the sequence. Thus,  $P$  is an IID (independent identical distribution) with  $P(1) = P(0) = 1/2$ .

(b)  $P$  assigns a probability of one to the class of sequences with a limiting frequency of  $1/2$  and a probability of zero to all other possible limiting frequencies; this follows from (a) by the strong law of large numbers.

### 3. No Free Lunch and Meta-induction – a Conflict?

We now turn to the relation between the weak no free lunch theorem and theorem 2 about meta-induction. The no free lunch theorem applies not only to object-level prediction methods, but also to all meta-strategies, given that they are applied to a *fixed* set of independent prediction methods – for the reason that every combination of a finite number of prediction algorithms is itself a prediction algorithm. So the puzzling question arises: If the

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<sup>1</sup>  $P$  yields Carnap's confirmation function  $c^\dagger$ . Technically,  $\{0,1\}^\omega$  is represented by the interval  $[0,1]$  of real numbers in binary representation (see fig. 1 below).  $P$  over the Borel algebra  $\text{Bo}([0,1])$  is defined by the integrals of an assumed density function  $D_P$  over  $[0,1]$ .

no free lunch theorem is true, how can it be that attractivity-weighted meta-induction, when applied to a fixed set of independent prediction algorithms, is dominant in comparison to certain other methods, as stated in theorem 2? Is this a contradiction?

Our answer to this question in regard to the long run perspective can be summarized as follows: No, the contradiction is only apparent. It is indeed true that there exist many wMI-accessible methods whose predictive success rate is (in the long run) strictly smaller than that of wMI in some worlds (event sequences)<sup>2</sup> and never greater than that of wMI in any world – let us call these methods  $M_{\text{inf}}$  (for "inferior"). Nevertheless the state-uniform expectation values of the success rates of wMI and  $M_{\text{inf}}$  are equal, because the state-uniform distribution that Wolpert assumes assigns a probability of zero to all worlds in which wMI dominates  $M_{\text{inf}}$ ; so these worlds do not affect the probabilistic expectation value.

Let us elaborate on this connection. The major difference between the account of meta-induction and Wolpert's extended Bayesian account is this: While the former account is independent from any assumed prior distribution over possible event sequences, Wolpert's result depends on a particular prior distribution, the *state-uniform* distribution. Wolpert seems to assume that this distribution is epistemically privileged. Reasonable doubts can be raised here, because the state-uniform distribution is induction-hostile. A proponent of this distribution believes with probability 1 a priori that the binary event sequence she is

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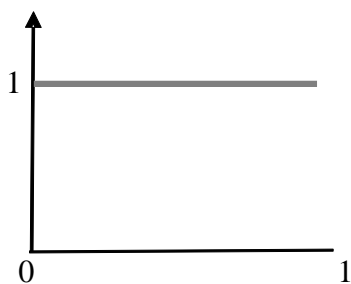
<sup>2</sup> Generally speaking possible worlds are identified prediction games. But in the given context we assume a fixed set of prediction methods, whence possible worlds can be identified with event sequences.

going to predict (a) has a limiting frequency of 1/2 and (b) is non-computable. Fact (a) follows from theorem 5, and (b) from the fact that there are uncountably many sequences, but only countably many computable ones. However, the event sequences for which an intelligent prediction method can be better than random guessing or any other stupid method are precisely those event sequences that *do not* fall into the intersection of classes (a) or (b). To make this point explicit: For random sequences with a limiting frequency of 1/2, all combinations of independent methods must have the same success rate as random guessing, i.e. 1/2. The only possibility for these sequences to be predictable is that they are computable by an internal regularity, but this possibility has probability zero, too.

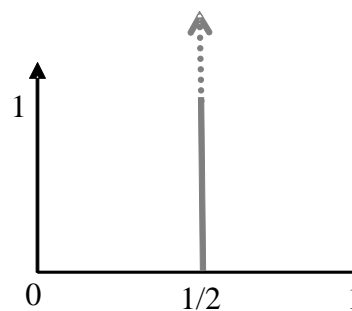
In conclusion, proponents of a state-uniform prior distribution are strongly biased: they are a priori certain that the world is irregular so that induction cannot have any chance. We suppose that adherents of a more induction-friendly view, for example Bayesians in the ordinary (not Wolpertian) sense, will regard a state-uniform prior distribution as highly "unnatural". Instead of a state-uniform distribution they typically prefer a uniform distribution over all possible limiting frequencies; we call such a distribution a *frequency-uniform* distribution. It is well known that frequency-uniform distributions are highly induction-friendly: from them one can derive Laplace's rule of induction,  $P(e_{n+1} = 1 \mid f_n(1) = \frac{k}{n}) = \frac{k+1}{n+2}$ , where " $f_n(1)$ " denotes the frequency of 1's among the first  $n$  events (cf. Carnap 1950, 568). In computer science, Laplace's rule has been generalized by Solomonoff (1964, sec. 4.1), who proved that if the prior probability of a sequence is inversely proportional to its *algorithmic complexity*, then Laplace's rule of induction is valid.

The precise relation between prior distributions over the space of possible infinite sequences and corresponding distributions over the space of possible limiting frequencies (or classes of sequences with the same frequency) is displayed in figures 1 and 2 below. As usual, infinite 0-1-sequences are represented as real numbers between 0 and 1 in binary representation (e.g., 0.0110...) and ordered according to their numerical size. In this way, the state-uniform distribution over possible sequences is represented as a uniform density over the interval  $[0,1]$ . Fig. 1 presents the transformation of this distribution into the corresponding distribution over possible limiting frequencies, with the result that a uniform distribution over  $[0,1]$  viewed as space of sequences is transformed into a maximally dogmatic distribution (an infinite density peak) over  $[0,1]$  viewed as space of frequency limits.

Uniform density over possible sequences (binary coding)



Corresponding 'maximally dogmatic' density over possible frequency limits



**Figure 1.** Transformation of a state-uniform into a frequency-uniform distribution.

Fig. 2 (below) illustrates the inverse transformation. The upper part of fig. 2 shows what happens to a frequency-uniform distribution over  $[0,1]$ , if it is transformed into a distribution over  $[0,1]$  viewed as space of possible sequences. The resulting distribution becomes

non-continuous and entirely disrupted: in every finite interval  $I \subseteq [0,1]$  it increases infinitely often to a positive value and falls back to zero.<sup>3</sup> It follows that a state-uniform prior distribution makes Bayesian converge results impossible, because all these results presuppose a (not necessarily uniform but) *continuous* prior distribution over the possible frequencies (cf. Earman 1992, 141ff). Thus "outwashing of priors" is impossible for state-uniform prior distributions. The lower part of fig. 2 displays Solomonoff's result (1964) which states that the frequency-uniform probability of a (finite or infinite) sequence decreases exponentially with its algorithmic complexity  $c(s)$ :  $P(s) \sim 2^{-c(s)}$ . Thus sequences with lower complexity have a higher frequency-uniform probability than those with high complexity. In conclusion, a frequency-uniform distribution is strongly biased in regard to less complex (more regular) sequences.

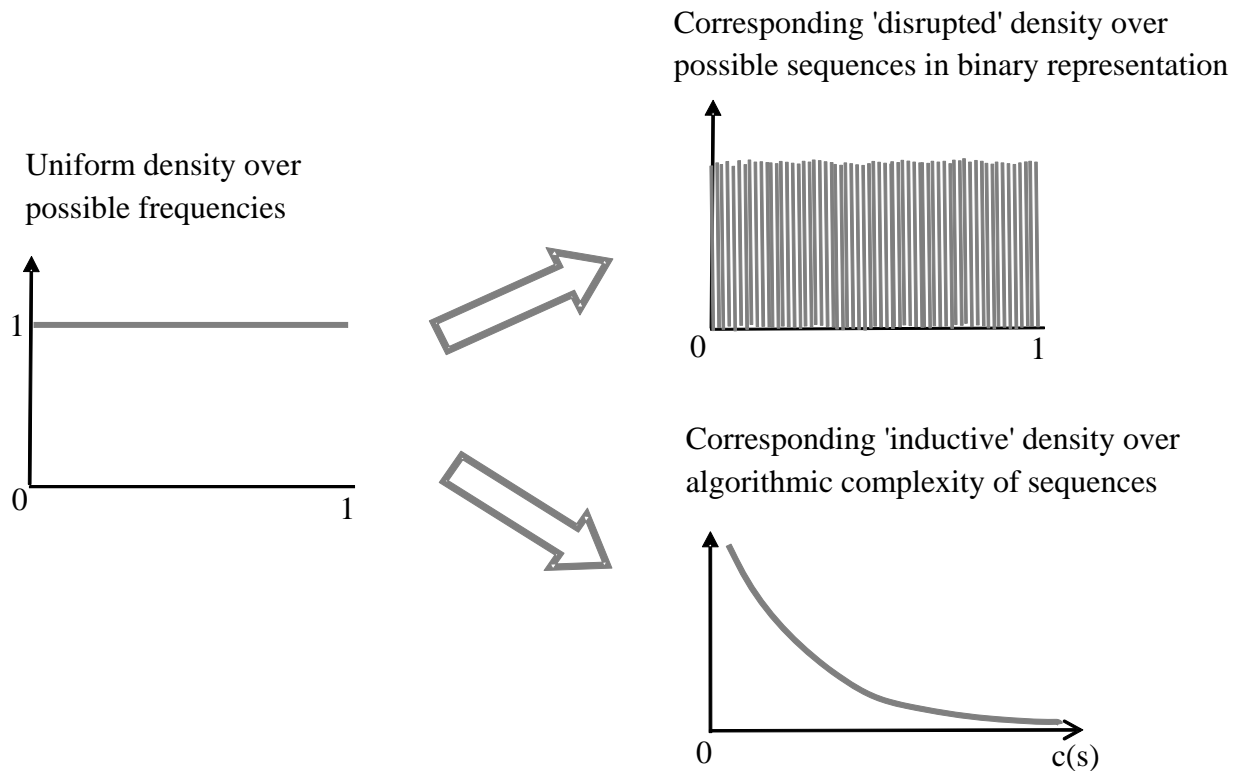
So which prior distributions are more natural, state-uniform ones or frequency-uniform ones? In our eyes, this question has no reasonable answer because all prior distributions are subjective and biased in some respect. We regard it as a great advantage of the optimality of meta-induction that it holds regardless of any assumed prior probability distribution. For a frequency-uniform prior distribution the probability of worlds in which meta-induction dominates random guessing is close to one. For a state-uniform prior the probability of

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<sup>3</sup>

To see this, let  $r_1$  and  $r_2$  ( $r_2 > r_1$ ) be two infinite sequences represented as binary real numbers  $r_1 = "0.00...(n \text{ times zero})11...(one \text{ forever})"$  and  $r_2 = "0.00...(n-1 \text{ times zero})11...(one \text{ forever})"$ . Their complexity is minimal. The class of sequences lying between  $r_1$  and  $r_2$  contains sequences with all complexities between the minimal one and the maximal one, which is possessed by sequences with frequency limit  $1/2$ . So the density climbs up and down between minimal and maximal complexity in the interval  $[r_1, r_2]$ . Since this holds for every arbitrary small interval, the claim follows.





**Figure 2.** Transformation of a frequency-uniform into –  
 upper part: – a state-uniform density distribution.  
 lower part: – a distribution over the algorithmic complexity.

worlds in which meta-induction dominates random guessing is zero. Nevertheless many such worlds exist and it is precisely in these worlds that intelligent prediction methods can have chance at all. We should certainly not exclude these induction-friendly worlds from the start by assigning a probability of zero to them. This concludes my discussion of the relation between meta-induction and the no free lunch theorem within the perspective of the long run.

#### 4. No Free Lunch and Meta-induction in the Short Run Perspective

The discussion of Wolpert's theorem within the perspective of the short run is more intricate. Recall that for finite sequences the advantage of meta-induction comes at a certain cost, that vanishes in the long run but is non-negligible for short sequences. Table 1 presents the result of a computer simulation of all possible prediction games with a length of 20 rounds, with binary events, three independent prediction methods and wMI.<sup>4</sup> The considered independent methods were

- majority induction, M-I, which always predicts the event that so far has been in the majority, and 0.5 in the case of ties (i.e.,  $\text{pred}_{n+1} = 1/0.5/0$  iff  $f_n(1) \geq / < 0.5$ , respectively),
- majority anti-induction, M-AI, which predicts the opposite of M-I (i.e.,  $\text{pred}_{n+1} = 0/0.5/1$  iff  $f_n(1) \geq / < 0.5$ , respectively),
- averaging, Av, which always predicts 0.5.

Table 1 displays the frequencies of sequences for which the absolute success of a prediction method lies in a certain interval that is specified at the left margin, with  $[0,1)$  being the lowest and  $[19,20]$  the highest possible success interval. In accordance with the weak no free lunch theorem one sees in the bottom line that the average success is the same for all four methods. Nevertheless the frequency distributions over classes of sequences in which these methods reach certain success levels is remarkably different. The averaging method predicts always 0.5 and earns a sum-of-scores of 10 in all possible sequences. The object-inductive method M-I reaches a high success level in more worlds than the anti-

inductive method M-AI (symmetrically, Av-AI attains a low success level in more worlds than Av-I). In compensation, the number of worlds in which the anti-inductive method does just a little better than averaging is significantly higher than the corresponding number of worlds for the inductive method.

	M-I	M-AI	Av	wMI
[0,1)	0	0.000	0	0
[1,2)	0	0.003	0	0
[2,3)	0	0.029	0	0
[3,4)	0	0.159	0	0
[4,5)	0	0.618	0	0
[5,6)	0.537	1.824	0	0
[6,7)	3.540	4.254	0	0
[7,8)	9.579	8.035	0	0
[8,9)	15.622	12.476	0	36.491
[9,10)	18.346	16.065	0	23.472
[10,11)	17.915	18.157	100.000	14.835
[11,12)	15.046	17.510	0	11.880
[12,13)	10.266	12.854	0	7.469
[13,14)	5.635	6.305	0	3.595
[14,15)	2.448	1.611	0	1.513
[15,16)	0.821	0.098	0	0.560
[16,17)	0.204	0	0	0.153
[17,18)	0.035	0	0	0.029
[18,19)	0.004	0	0	0.003
[19,20)	0	0	0	0
State-uniform average	10	10	10	10

**Table 1.** Computer simulation of M-I, M-AI, Av and wMI in all ( $2^{20}$ ) binary sequences with 20 rounds. Cells show percentage of sequences in which certain levels of absolute success (left margin) have been reached.

Based on these results we obtain a justification of object-induction and of meta-

induction *even within* the induction-hostile perspective of a state-uniform prior distribution for *short-run* sequences. One can reasonably argue that what counts is to reach *high* success in those environments which *allow* for high success. This is what independent inductive methods do. At the same time one should *protect* oneself against *low* successes – this is what cautious methods of the type "averaging" do. The advantage of wMI meta-induction is that it combines *both* – reaching high successes where it is possible (inspect the intervals [12,13)–[19,20]) and at the same time avoiding low successes (inspect the intervals [8,9) and [9,10)). Thus wMI achieves "the best of both worlds". This, however, goes on the cost of a certain short-run loss (inspect the intervals [10,11) and [11,12)).

## 5. Conclusion

In this paper we confronted the optimality of meta-induction with the no free lunch theorem. We demonstrated that the apparent conflict between these two results disappears when one considers that the no free lunch theorem assumes a state-uniform prior distribution over the set of all (binary) event sequences. This distribution assigns a probability of zero to all infinite sequences that exhibit some sort of regularity which an intelligent prediction method could exploit. Short sequences were investigated by means of a computer simulation of all possible sequences of length 20. The result shows that in spite of having an equal expected predictive success, different prediction methods differ significantly in the frequency with which they reach certain success levels. Meta-induction turns out to offer the best combination of two abilities: exploiting regular sequences and avoiding loss-

es in irregular sequences.

We emphasize that this characterization of the advantage of meta-induction holds for the induction-hostile state-uniform prior distribution. If one switches to a frequency-uniform prior distribution, the computer simulation produces rather different results: Now M-I and wMI have highest predictive success in all classes of sequences whose frequencies are in the intervals  $[0,0.1)$ , ...,  $[0.3,0.4)$  and  $[0.6,0.7)$ , ...,  $[0.9,1]$ . wMI suffers from a small loss compared to M-I in these frequency intervals. In the frequency intervals  $[0.4,0.5)$  and  $[0.5,0.6)$  the picture is reversed: Here M-AI and Av are more successful than M-I; wMI suffers from a small loss compared to M-AI and Av, but is more successful than M-I. Because of space limitations we abstain from presenting the details.

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