

What's on the inside counts: A grounded account of concept acquisition and development

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What's on the inside counts: a grounded account of concept acquisition and development

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2 ABSTRACT

3 Understanding the factors which affect the age of acquisition (AoA) of words and concepts
4 is fundamental to understanding cognitive development more broadly. Traditionally, studies
5 of AoA have taken two approaches, either exploring the effect of linguistic variables such as
6 input frequency (e.g., Naigles and Hoff-Ginsberg, 1998) or the semantics of the underlying
7 concept, such as concreteness or imageability (e.g., Bird et al., 2001). Embodied theories of
8 cognition, meanwhile, assume that concepts, even relatively abstract ones, can be grounded in
9 the embodied experience. While the focus of such discussions has been mainly on grounding in
10 external modalities, more recently some have argued for the importance of interoceptive features,
11 or grounding in complex modalities such as social interaction.

12 In this paper, we argue for the integration and extension of these two strands of research. We
13 demonstrate that the psycholinguistic factors traditionally considered to determine AoA are far
14 from sufficient to account for the variability observed in AoA data. Given this gap, we propose
15 *groundability as a new conceptual tool that can measure* the degree to which concepts are
16 grounded both in external and, critically, internal modalities. We then present a mechanistic theory
17 of conceptual representation that can account for groundability in addition to the existing variables
18 argued to influence concept acquisition in both the developmental and embodied cognition
19 literatures, and discuss its implications for future work in concept and cognitive development.

20 **Keywords:** Concept grounding; embodiment; developmental linguistics; age of acquisition; SPAa

1 INTRODUCTION

21 Within representationalist theories of embodied cognition, the symbol grounding problem has traditionally
22 received much attention. The reason for the focus can be understood from a historical perspective: as
23 Chemero (2009) notes, these theories developed primarily as a reaction to purely computationalist views
24 of cognition¹. One of the main criticisms levelled at such views was that they assume amodal symbols
25 which are meaningless to the system itself – whatever meaning the symbols might carry was attributed by

¹ In contrast, non-representationalist theories of embodied cognition are an evolution of Ecological Psychology and its precursors.

26 external observers. How such symbols could acquire meaning that is intrinsic to the system became known
27 as the symbol grounding problem (Harnad, 1990), and the central claim to the solution in embodied terms
28 is that the meaning is acquired through sensorimotor interaction with the world.

29 This has led to at least two major research strands. On the more experimental end of the spectrum,
30 much work has focused on detailing the involvement of sensorimotor areas of the brain in, for instance,
31 language processing (see Chersi et al., 2010, for a review). Although such involvement is often taken as
32 evidence for a grounded or embodied understanding of concepts, it is worth pointing out that this is not
33 uncontroversial: Mahon and Caramazza (2008), for instance argue, that the evidence is not sufficient to
34 invalidate disembodied hypotheses.

35 On the computational end of the spectrum, researchers are interested in creating models of symbol
36 grounding. Eliasmith (2013), for example, details a “semantic pointer architecture”, which provides a
37 computational implementation of many aspects of Barsalou’s perceptual symbol system (Barsalou, 1999).
38 Other efforts consider robotic implementations of such models (see, for instance, Stramandinoli et al.,
39 2012, or, for a review, Coradeschi et al. 2013).

40 A particularly interesting aspect of research across the entire spectrum concerns the putative grounding
41 of abstract concepts – that is, concepts which do not have a directly perceivable sensorimotor target (see,
42 for instance Thill et al., 2014; Dove, 2011, for recent reviews and discussions). While it is relatively
43 straightforward to propose accounts of sensorimotor grounding of concrete concepts – which do have
44 an observable sensorimotor target in the external world – it is less clear how, if at all, abstract concepts
45 should relate to embodied experience. Mahon and Caramazza (2008) give the example of the concept
46 “beautiful”, for which they claim that there is no corresponding *consistent* sensory or motor information
47 (their emphasis).

48 An early attempt at explanation is given by the conceptual metaphor theory (Lakoff and Johnson, 1980),
49 which postulates that metaphors and analogical reasoning (*e.g.*: an argument is like war; happiness is up)
50 mediate grounding of abstract concepts in direct sensorimotor experience. However, Dove (2011) points
51 out that the required cognitive mechanisms, such the ability to construct such analogies and metaphors, are
52 not likely to develop until relatively late. He further argues that linguistic representations are dis-embodied
53 (the specific term he coined, and distinct from disembodied) in the sense that they do not acquire semantic
54 content from embodiment, even though they may remain dynamic, multimodal **and grounded in linguistic**
55 **experience. Zwaan (2015) also argues that abstract concepts “acquire a specific sensorimotor instantiation**
56 **in a discourse context” while being only weakly associated with sensorimotor representations.** Similarly,
57 Barsalou et al. (2008) previously proposed the Language And Situated Simulation (LASS) theory, arguing
58 that both linguistic forms and situated simulations are used to represent concepts, including abstract ones.

59 Other theories imply that the grounding of more abstract concepts can take place in modalities beyond the
60 five senses in the strict sense. The Words As Tools theory (WAT Borghi and Binkofski, 2014) sees words
61 as social tools, whose use is a “type of experience” (Borghi and Cimatti, 2012, p.22), which provides a
62 potential way of grounding abstract concepts in a type of social modality. Similarly, Thill et al. (2014) argue
63 that one should not restrict the embodied experience to the “outside” in a theory of concept grounding **while**
64 **Wellsby and Pexman (2014a) note that the focus so far has been more on interaction with the external world**
65 **and less on “sensing bodies” (their term). This is also true for theories that try to link abstract concepts to**
66 **embodiment, for instance by grounding them in the sensorimotor representations activated across different**
67 **linguistic contexts (Barsalou and Wiemer-Hastings, 2005; Zwaan, 2015).** As others have noted, the human
68 embodied experience is actually very rich and involves many internal processes (see Stapleton, 2011, 2013,

69 for a thorough review and discussion), including homeostatic and affective mechanisms (e.g. Damasio,
70 2010; Ziemke and Lowe, 2009) which may directly ground concepts that are considered abstract. As
71 noted by Stapleton (2013), the *internal body* may² matter to cognition. **Of the aspects that comprise this**
72 **internal body, affect and emotion have received the most attention in discussions of concept grounding so**
73 **far. Glenberg and Gallese (2012), for instance, propose an account of language acquisition that includes**
74 **emotional systems as a providing means for grounding in addition to perception and action. Similarly,**
75 **Kousta et al. (2011) argue that abstract words tend to be more emotionally valenced than concrete ones, and**
76 **that *emotional content* might be an important factor in the representation and processing of abstract words**
77 **in particular. Newcombe et al. (2012) showed a correspondence between emotional experience and speed**
78 **(and accuracy) of classification of abstract – but not concrete – words, and argue that abstract concepts**
79 **may be grounded in emotional features that remain stable across different contexts (see also Siakaluk et al.,**
80 **2014, for a follow-up). The concept of “beautiful”, although having no consistent *external* sensorimotor**
81 **experience, may thus relate to direct internal experience.**

82 Research into concept grounding tends to focus on adult language and cognition. There are, however, good
83 reasons to approach the topic from a developmental perspective (Kontra et al., 2012). Most immediately,
84 any mechanistic account of concept grounding makes the direct prediction that whatever mechanism is
85 proposed has developed by the time that humans use that concept – recall, for example, Dove’s (2011)
86 concern regarding the use of metaphors previously mentioned. Second, bodily and cognitive development
87 may be a crucial component for explanatory accounts of cognitive mechanisms: after all, humans acquire
88 concepts during a period of dramatic change.

89 Concept grounding depends, by definition, on the sensorimotor experience that is meant to provide this
90 grounding. The importance of this embodied input has been accepted since Piaget’s classic work on the
91 sensorimotor roots of cognitive development (Piaget, 1952). More recently, however, new technology has
92 provided striking novel insights into the infant’s embodied experience: that is, what infants experience is
93 substantially different from what adults experience. As the body changes – e.g. arms grow longer, walking
94 commences – so too do important characteristics of the body-mediated information available for concept
95 grounding. Studies using head-mounted eye trackers demonstrate, for example, that the content of the
96 infant’s visual field is qualitatively and quantitatively different from that of the adult, because infants’
97 shorter arms lead them to hold objects close to their faces (Smith et al., 2011). The precise nature of the
98 body (e.g., walking vs. crawling, height) is clearly crucial in shaping this experience (Kretch et al., 2014);
99 yet it is also often ignored in the embodied cognitive science literature. For instance, Ziemke (2003) points
100 out that “many discussions/notions of *embodied* cognition actually pay relatively little attention to the
101 nature and the role of the body involved (if at all)” (p 1306, emphasis in text) and Borghi et al. (2013)
102 similarly argues that “many versions of the [embodied-grounded] view are too brainbound” (p 2).

103 The developmental psychology literature also features a substantial body of work concerned with human
104 concept and word acquisition. This work is highly relevant to the concept grounding discussion. In
105 particular, it illustrates how change over time in the conceptual system reflects change over time in the
106 physical system. For instance, conceptual structure changes radically across development (Mandler, 2000;
107 Quinn and Eimas, 1997): infants as young as three months form perceptually-based categories (Quinn et al.,
108 1993), but begin to show evidence of more abstract representations by around 12 months (Mandler and
109 Bauer, 1988), and make conceptually-based category judgements by four years (Keil, 1989). Importantly,

² Stapleton (2013) actually omits the “may”, stating that “I argue that recent work in neuroscience and robotics suggests cognitive systems are not merely superficially embodied in the sense that the sensorimotor interactions with the environment are the only interactions relevant to cognitive behaviour, but that cognitive systems are ‘properly embodied’; the internal body matters to cognition” (p 1–2)

110 early perceptual/conceptual structure and language acquisition are intimately linked. For example, by
111 drawing attention to invariant, category-relevant features, perceptual variability in the objects children see
112 supports category formation and subsequent word learning (e.g. Goldenberg and Johnson, 2015; Twomey
113 et al., 2014; Vlach et al., 2008). Relatedly, English-learning children generalize category labels to new
114 same-shape items, but only if those items are solid rather than nonsolid (Samuelson and Horst, 2007).
115 Further, variation in the physical position of the body can disrupt word learning (Samuelson et al., 2011;
116 Morse et al., 2015). Thus, evidence from multiple modalities indicates that the perceptually grounded
117 nature of early concrete concepts interacts with children's ability to learn words. Indeed, the interaction
118 between perceptual grounding and early language has been investigated. For example, in a word naming
119 study which included school-age children, Wellsby and Pexman (2014b) demonstrated that the extent to
120 which the referents of words are easy to physically interact with (as rated by adults) affected 8- to 9-year
121 old children's written word processing. Specifically, children's naming latencies were shorter for words
122 with high body-object-interaction (BOI) ratings. The authors argued that high-BOI words have richer
123 semantic representations than low-BOI words, leading to greater activation in the semantic system, which
124 in turn facilitates word recognition. Taken together with the adult literature, the developmental embodied
125 cognition approach makes the prediction that the sensorimotor experience associated with a concept should
126 affect how easy it is to acquire that concept.

127 Recent psycholinguistic studies have focused on the age of acquisition (AoA) of words as a marker
128 of concept learning, and demonstrate that the semantic features of concepts themselves affect the age at
129 which their labels are learned. For example, McDonough et al. (2011) examined the effect of a word's
130 imageability (the extent to which a word generates a mental image Paivio et al., 1968) and class (e.g.,
131 noun, verb) on AoA. As well as predicting AoA, imageability accounted for variation that word class did
132 not, indicating an independent role of perceptual features in the acquisition of early abstract concepts (for
133 crosslinguistic evidence, see Ma et al., 2009). Closely related to imageability is concreteness, or the extent
134 to which a concept is perceptible (Brysbaert et al., 2014). Bird et al. (2001) showed that imageability and
135 concreteness predicted AoA for children's early-produced nouns (see also Barca et al., 2002; Smolík, 2014).
136 In a study in which Dutch adults rated words for emotional valence, arousal, power and AoA, valence
137 was negatively correlated with AoA such that more positive words were acquired earlier (Moors et al.,
138 2013). In addition, linguistic phenomena also affect AoA, including – but not limited to – iconicity (Perry
139 et al., 2015), and in particular, input frequency (Ambridge et al., 2015; Barca et al., 2002; Goodman et al.,
140 2008; Naigles and Hoff-Ginsberg, 1998; Storkel, 2004; Roy et al., 2015). Whether sensorimotor experience
141 predicts AoA, however, remains to be tested.

142 In the following section we bring together in a single analysis variables that have been shown to affect
143 AoA, specifically, frequency, imageability and valence. Our goal is not to provide an exhaustive account
144 of conceptual and linguistic influences on AoA; indeed, for many of these variables insufficient data
145 are available for a reliable analysis. However, to our knowledge this is the first study to bring together
146 these variables in analysing the reliable measure of AoA provided by the widely-used MacArthur-Bates
147 Communicative Development Inventory vocabulary norms (Fenson et al., 1993). We demonstrate that,
148 when taken together, these variables explain only a minority of the variance, highlighting the importance of
149 identifying and testing new factors. In a second analysis we test our hypothesis that sensorimotor grounding
150 is important to AoA, by adding a measure of body-object interaction. We argue that while existing measures
151 take into account conceptual and linguistic effects on AoA, embodied characteristics of concepts may be
152 an important missing piece of the puzzle.

2 METHODS

153 To explore the effect of conceptual features on AoA we obtained AoA, frequency, imageability and valence
154 ratings from a range of open access sources. **Data used in the analyses are provided in Appendix A and**
155 **Pearson correlations between variables are presented in Table 1.**

156 2.1 Age of Acquisition

157 Our goal was to explore the extent to which previously identified variables predict the age of acquisition
158 of words commonly learned by human infants. We took our target words from the MacArthur Bates
159 Communicative Development Inventory (MCDI; Fenson et al., 1993). The MCDI is a well-established,
160 normed and validated list of 680 words that infants and toddlers learn to understand and produce up to 30
161 months of age, and is widely used in developmental research. We defined AoA as the month in which 50%
162 or more of 1,142 infants in the MCDI sample produced a given word. AoA in months ranged from 12 (e.g.,
163 *mommy*) to 30+ (e.g., *pretend*). AoAs listed as 30+ months were coded as 31 months for the purposes of
164 the current analysis.

165 2.2 Frequency

166 Children's language environment has been repeatedly shown to influence their language acquisition
167 (for a review, see Ambridge et al., 2015). We therefore generated our frequency data from real child-
168 directed input, which is representative of the language children hear, rather than relying on corpora of
169 non-child-directed spoken or written speech. CHILDES (MacWhinney, 2000) is a large, open-access online
170 database of transcribed, naturalistic conversations between adults and children. We searched all Northern
171 American corpora for each word in the MCDI, with the exception of some sound effects and routines (e.g.,
172 *woof*, *patty cake*). Only mothers' utterances were queried, providing an index of children's input. This
173 resulted in frequency ratings for 638 words with frequencies ranging from 0 (*cat*) to 128124 (*you*) tokens
174 ($M = 2848.82$).

175 2.3 Imageability and concreteness

176 For each MCDI word for which we obtained frequency data we extracted imageability and concreteness
177 ratings from the MRC Psycholinguistic Database (Coltheart, 1981; Wilson, 1988). The database is a large,
178 open-access collection of 26 psycholinguistic variables for up to 150,000 words (although not all words
179 have data for all variables) aggregated from existing studies³. Because imageability and concreteness were
180 very highly correlated ($r = .91$, $p < .0001$), in line with Ma et al. (2009) and McDonough et al. (2011),
181 we used imageability as a predictor variable in the following analyses. Imageability scores ranged from
182 195 (low) to 667 (high; $M = 495.58$).

183 2.4 Valence

184 Valence ratings for each word were taken from the 2010 version of the Affective Norms for English
185 Words dataset (ANEW; Bradley and Lang, 2010). This version of ANEW consists of adult ratings of
186 2,476 words for pleasure (i.e., valence), arousal and dominance. Scores ranged from 1.61 (happy) to 8.72
187 (unhappy; $M = 5.92$).

³ details available at http://www.psych.rl.ac.uk/MRC_Psych_Db_files/mrc2.html

188 2.5 Body-object interaction

189 To explore our hypothesis that sensorimotor grounding may be important for concept acquisition, we
190 took measures of body-object interaction (*BOI*) from Tillotson et al. (2008) and Bennett et al. (2011), in
191 which adults were asked to rate the extent to which they could easily interact with a named item. Scores
192 ranged from 1.27 (*first*; low interactivity) to 6.43 (*doll*; high interactivity; $M = 4.68$). Specifically, our
193 assumption is that the experience of interacting with concepts that rate highly is more multi-modal than
194 that of interacting with low-ranking concepts (if such an experience exists at all), so *BOI* might serve as a
195 proxy to rank concepts by how much they are defined by an external sensorimotor experience.

3 RESULTS

196 3.1 The effect of conceptual features on AoA

197 To explore the effect of conceptual features on AoA, we first created a *conceptual features model*. AoA
198 for the 398 words with ratings for every variable was submitted to a linear regression with frequency
199 (log transformed), imageability (mean centred) and valence (mean centred) as fixed effects. Because
200 high frequency function words have little or no semantic content, while rarer nouns have rich semantics,
201 we anticipated that frequency and imageability would interact, so included a frequency-by-imageability
202 interaction term (cf. Roy et al., 2015).

203 Results are presented in Table 2. The principal result is that the interaction between frequency and
204 imageability predicts AoA, extending the findings of McDonough et al. (2011) and Ma et al. (2009), who
205 each found correlations between CDI AoA and imageability ratings. As illustrated in Figure 1, although
206 late-acquired words tend to be lower frequency, function words (e.g., *an*, *the*, *to*) have low imageability and
207 are acquired late despite being high frequency. In contrast, high-imageability words for the things infants
208 encounter in their everyday environment (e.g., *puppy*) are acquired early despite occurring infrequently.
209 In addition to the interaction between imageability and frequency, main effects of these two variables
210 confirmed that as imageability increased, AoA decreased (see also Ma et al., 2009; McDonough et al.,
211 2011), and in line with Roy et al. (2015), as frequency increased, AoA decreased. Interestingly, in contrast
212 with existing studies (e.g., Bird et al., 2001; Moors et al., 2013), valence did not predict AoA; however
213 the adult ratings we used may not capture the effect of a word's valence on young children. More broadly,
214 the differences between our results and existing studies may stem from some important methodological
215 differences: while the majority of work uses adult ratings of word AoA and frequency measures taken
216 from corpora of adult-directed language, we use parental measures of their own children's language and
217 frequencies taken from child-directed speech (cf. McDonough et al., 2011). This contrast highlights the
218 need for child-centric ratings of such predictors, and illustrates the importance of taking seriously the real
219 input to infants when investigating developmental phenomena (Smith et al., 2011).

220 The goal of this analysis was to illustrate that even well-tested predictors are unable to fully explain
221 AoA. As expected, this model accounted for less than half of the variance (adjusted $R^2 = 0.38$), leaving
222 substantial scope for the influence of other factors on early concept acquisition. As noted above, our
223 analysis focuses on variables which have repeatedly been shown to influence AoA, and ignores those for
224 which no data are available. Thus, we do not claim that it is an exhaustive model of the factors affecting
225 concept AoA. We do, however, argue that the variance unaccounted for is not simply random variation, but
226 rather the result of linguistic and concept-internal variables not typically included in analyses of AoA. In
227 particular, this leaves open the possibility that embodied aspects of concepts may contribute to the ease
228 with which they are acquired.

229 3.2 The effect of a sensorimotor grounding on AoA

230 To explore whether **the extent of** sensorimotor grounding might play a role in concept acquisition (**as**
231 **discussed in section 2.5**), we added a measure of body-object interaction as a predictor in the conceptual
232 features model to create a *BOI model*. Because fewer of our target words had ratings for this variable, the
233 final dataset for this analysis consisted of complete ratings for 151 words.

234 As illustrated in Table 3, when the additional BOI term is included, the frequency-by-imageability
235 interaction and main effect of imageability predict AoA, while the main effect of frequency does not.
236 Critically, in line with our predictions, BOI does predict AoA, such that as words are rated as more difficult
237 to interact with, AoA **increases**. Importantly, this model also explained a greater proportion of the variance
238 in AoA, with an increase in adjusted R-squared from 0.38 to 0.40. To compare the fit of our two models,
239 we first refit the conceptual features model to the smaller dataset; this resulted in a similar pattern of
240 results (see Table 4). Including the BOI term resulted in a reduction in AIC from 788.43 to 770.80. Taken
241 together with the increase in adjusted R-squared, this confirms that the BOI model fits the data better,
242 explaining more variance than the conceptual features model and supporting our claim that the extent to
243 which concepts are grounded in the body affects AoA.

244 Although including BOI improved the fit of the model, it nonetheless again left a majority of the variance
245 unaccounted for – as expected, given that it did not include linguistic effects on AoA, for example iconicity
246 (Perry et al., 2015), ease of pronunciation (Jorm, 1991) and contextual diversity (Hills et al., 2009), **and the**
247 **fact that these ratings came from adults. Thus, it is, for example, possible that using child ratings of BOI**
248 **could improve the model fit further.** What drives concept AoA is far from being fully understood; however
249 the above analyses strongly suggest that grounding in sensorimotor experience could be a critical piece in
250 this puzzle.

4 WHAT ARE CONCEPTS MADE OF?

251 To summarise the results, we first showed that semantic features and linguistic phenomena such as frequency
252 are not sufficient to explain AoA data. Our main hypothesis is that this is because such features do not take
253 into account grounding in a rich or proper **sensorimotor experience**. We then demonstrated that including
254 predictors related to such a grounding improve on the initial results.

255 There is clearly much work to be done to validate the hypothesis further. First and foremost, there are
256 currently no major corpora of data that relate to relevant measures other than BOI as used above. Second,
257 the measure of BOI used above takes no account of interoceptive aspects of **the sensorimotor experience**,
258 which, as noted, are likely to play a part in conceptual structure. **How to tap into such interoceptive aspects**
259 **is not trivial. Although valence ratings may seem like a good starting point (since valence itself is part**
260 **of the internal sensory experience), they do not provide a measure of how diverse (or multi-modal) the**
261 **internal sensory experience associated with a concept is⁴. Instead, they quantify the strength of one aspect**
262 **(which is clearly relevant, as argued for instance by Kousta et al., 2011, but not necessarily sufficient**
263 **since there are other internal modalities as discussed, for example, by Stapleton 2011). Together with the**
264 **limitations of BOI mentioned before, there is therefore still a need for designing new types of measures**
265 **that address both internal and external sensorimotor experience more explicitly.**

266 The purpose of the remainder of this paper is therefore to outline a mechanism of concept learning
267 which explicitly takes into account embodied features beyond simple sensorimotor interaction (for instance,

⁴ in PAD space (Mehrabian and Russell, 1974), for example, valence ratings do not relate to the A or the D

268 interoceptive features) whilst incorporating the variables which have been repeatedly shown to affect AoA,
 269 and by extension, conceptual development and structure. In doing so, we will generate testable predictions
 270 for future work and lay the groundwork for future research into novel measures that can validate our
 271 hypothesis.

272 To provide this characterisation, we cast our discussion in terms of a cognitive architecture since these
 273 necessarily formally specify the mechanisms underlying concept use. Specifically, we base our discussion
 274 on the semantic pointer architecture (SPA, see Eliasmith, 2013). It would of course be equally possible
 275 to formulate these ideas in frameworks other than SPA; the Neural Blackboard Architecture framework
 276 (van der Velde and de Kamps, 2006), for example, is also concerned with the creation of combinatorial
 277 structures, such as concepts, that might underlie human cognition. For the present purposes, however, we
 278 think SPA well-suited: it is inspired by human semantics and syntax in that its “semantic pointers” can be
 279 interpreted as perceptually grounded symbols in the sense of Barsalou (1999). SPA can also incorporate
 280 mechanisms necessary for concept grounding in terms of a rich **sensorimotor experience** (see Thill, 2015,
 281 for a longer discussion).

282 The question of when children acquire concepts can therefore be reformulated, for the present purposes, as
 283 asking at what age the corresponding semantic pointer forms. In the following, we first give a brief overview
 284 of the main computational principles in SPA (we refer the interested reader to Eliasmith, 2013, for a much
 285 more thorough discussion, including various demonstrations of cognitive and biological plausibility). We
 286 then provide the aforementioned characterisation of concepts, which finally allows us to highlight directions
 287 for future work.

288 4.1 Brief overview of semantic pointers

289 Semantic pointers, in SPA, are vectors in a high-dimensional⁵ space. **For example, the concept of a**
 290 **robin would thus be described by a vector robin. To specify how such a vector might be obtained, SPA**
 291 **takes inspiration from hierarchical structures in the human brain such as the visual cortex (Felleman**
 292 **and Van Essen, 1991). For example, the retinal image of a robin is successively compressed through the**
 293 **different layers of the hierarchy for object recognition (V1 → V2 → V4 → IT) into a representation with**
 294 **significantly lower dimensionality than the original retinal input. This resulting representation at the top of**
 295 **the hierarchy would be a semantic pointer robVis encoding the visual appearance of a robin.**

Multiple representations can then be bound together to form a new concept. In SPA, the binding operator is *circular convolution*, denoted by \otimes , a vector operation which takes two vectors as an input and returns a vector of the same length as an output. To give an example from Eliasmith (2013), one could construct a semantic pointer for perceptual features of a robin:

$$\mathbf{robinPercept} = \mathbf{visual} \otimes \mathbf{robVis} + \mathbf{auditory} \otimes \mathbf{robAud} + \mathbf{tactile} \otimes \mathbf{robTact} + \dots$$

where each element in bold represents a semantic pointer. **robin** could then be defined as:

$$\mathbf{robin} = \mathbf{perceptual} \otimes \mathbf{robinPercept} + \mathbf{isA} \otimes \mathbf{bird} + \mathbf{indicates} \otimes \mathbf{spring} + \dots$$

296 **There are several aspects of semantic pointers that we do not discuss here. It is, for example, possible to**
 297 **“read out” particular components of a semantic pointer (such as what the visual percept RobinVis within**
 298 **the overall concept of Robin is), and to recall the visual image(s) used in forming that particular pointer –**

⁵ Eliasmith (2013) suggests that 500 dimensions are sufficient for human cognition

299 a process that can be interpreted as a type of simulation of previous sensorimotor experience as proposed
 300 by Barsalou (Barsalou, 1999; Barsalou and Wiemer-Hastings, 2005; Barsalou, 2009). Further discussions
 301 of the underlying neural structures, necessary neural mechanisms, and biological plausibility can be found
 302 in Eliasmith (2013).

303 For the present purposes, it is also worth emphasising that, although it is capable of symbolic manipulation,
 304 SPA is not a symbolic account of cognition; the semantic pointers related to any concept are not arbitrary
 305 symbols but *a compressed combination of perceptual features that make up the concept*. As such, the
 306 sensorimotor experience of a given concept by an agent plays a fundamental role in forming the concept
 307 and shaping computations that use it.

308 4.2 Characterisation of richly grounded concepts

309 In essence, we argue throughout this paper that sensorimotor concept grounding requires a rich perspective
 310 of what the term “sensorimotor” actually entails: it is not merely sufficient to consider basic sensorimotor
 311 interaction with the external world; internal percepts (including affect, emotional components and other
 312 aspects of interoception as discussed in more detail, for example, by Stapleton, 2011) are equally important
 313 (Thill et al., 2014; Wellsby and Pexman, 2014a). We therefore postulate that the sensory features of a
 314 concept, directly perceived at a given time t , can be described as follows:

$$S_t^D = \sum_i \sum_j \text{Modality}_i^{\text{ext}} \otimes \text{feature}_j + \sum_k \sum_l \text{Modality}_k^{\text{int}} \otimes \text{feature}_l \quad (1)$$

315 where we omit an explicit mention of time on the RHS. Eqn. 1 simply captures the idea that concepts
 316 are multimodal and made up of any number of features from any number of modalities (notably, this
 317 number can also be low: constructs are not necessarily complex. In particular, a concept could consist of a
 318 single modality, for example the concept “yellow”). What matters is the direct nature of these features; by
 319 which we mean that they are not time-dependent. They could for instance relate to a colour or the shape
 320 of a solid object, as acquired by the visual modality, the smoothness of a surface from a tactile modality,
 321 or an affordance elicited by a given object. They could equally relate to direct visceral feelings elicited
 322 when experiencing, for example, surprise, pleasure, or to the proprioceptive feeling of an extended arm.
 323 Affective mechanisms or emotional components (as highlighted by many, e.g. Glenberg and Gallese, 2012;
 324 Newcombe et al., 2012; Kousta et al., 2011) of concepts can be included by representing the different
 325 dimensions as internal modalities. For example, in PAD Space (Mehrabian and Russell, 1974), one might
 326 posit the following: **Pleasure** \otimes value_p + **Arousal** \otimes value_a + **Dominance** \otimes value_d .

327 Other sensorimotor perceptions, on the other hand, are time-dependent: movements are, for example, by
 328 definition expressed over time. We sketch such percepts as:

$$S^T = f \left(S_{t=1, \dots, n}^D \right) \quad (2)$$

329 where the notation again chooses simplicity over being explicit since it is merely meant to be a sketch of a
 330 process that would capture temporal aspects of percepts. Here, $f(\cdot)$ is therefore a simply placeholder for a
 331 temporal function (see, for example, Pack and Bensmaia, 2015, for a discussion of neural sensitivity to
 332 temporal stimuli, and underlying computations, in both the visual and touch modalities).

333 We argue that Eqns. 1 and 2 provide a reasonable characterisation of the sensorimotor experience that
 334 may ground concepts and provides a starting point for analysing concept acquisition. To address word

335 acquisition proper, we also need to recognise that verbal labels can be attached to concepts. This gives us
 336 the first expression for a concept grounded in rich sensorimotor experience:

$$C = S^D + S^T + \text{Label} \otimes \text{name} \quad (3)$$

337 Next, we note that pointers in SPA can be constructed from other pointers, as in the previous example of
 338 the robin. We can introduce a similar idea here by noting that a given concept can be made up by more
 339 than just direct sensory features; it can equally include existing concepts:

$$C = S^D + S^T + \sum_i \sum_j \text{Includes}_i \otimes C_j + \text{Label} \otimes \text{composite} \quad (4)$$

340 where we highlight that other concepts are not merely added by summation (see Eliasmith, 2013); it
 341 is rather the compressed vector that is added as a property (that we refer to as **Includes** here). Eqn. 4
 342 also captures how some researchers, (particularly those primarily interested in robotic models of concept
 343 grounding) believe abstract concepts can be grounded (see Stramandinoli et al., 2012, for an example and
 344 Thill et al. 2014 for a larger discussion). In such theories, rather than being grounded in direct sensorimotor
 345 features, abstract (or higher order) concepts are instead grounded in other concepts, possibly with no direct
 346 sensorimotor component at all, meaning the first two terms on the RHS of Eqn. 4 would be empty.

347 In sum, we argue that Eqn. 4 describes the general form of a grounded concept, can accommodate
 348 current views on concepts, can account for abstract concept acquisition, and allows us to incorporate a rich
 349 embodied experience without positing a separate mechanism. For example, the modalities that provide
 350 features can extend to the social domain, in line with claims that more abstract words go beyond the simple
 351 sensorimotor to include a stronger social component (Borghi and Binkofski, 2014; Borghi and Cimatti,
 352 2009, 2012). It is also worth highlighting that the characterisation does not require *all* components to
 353 be related to some form of sensorimotor experience (even if rich). The use of **Includes** allows for the
 354 inclusion of purely linguistic features (Kousta et al., 2011), which in turn allows for dis-embodied concepts
 355 in the sense of Dove (2011). Indeed, in any of the above, the left-hand term of the \otimes operator in SPA
 356 could in principle refer to anything and does not necessarily need to be itself something that has a direct
 357 sensorimotor grounding (as is clear from the robin example above). This therefore also allows for the
 358 construction of metaphors in the sense of Lakoff and Johnson (1980) – as a crude example, one could for
 359 instance postulate the following:

$$\text{Happiness} \approx \text{Modality}^{\text{int}} \otimes \text{Up} \quad (5)$$

360 which is meant to express that happiness causes interoceptive feelings that are somewhat akin to the
 361 grounded concept of “Up”. **Up**, here is a concept as described by Eqn. 4.

362 Finally, it is worth pointing out that this characterisation is open to the use of purely amodal symbols,
 363 perhaps even in conjunction with grounded ones. Exploring this further would require a theory of how such
 364 semantic pointers are formed, but once they are, they could be used at the appropriate places in Eqns. 1 – 4
 365 (where one could for instance imagine a dedicated modality for amodal symbols). We do not pursue this
 366 here since our main aim is to discuss the grounding of concepts.

5 DISCUSSION

367 Having characterised concepts in terms of the semantic pointer architecture, we now turn to ways in which
368 it can contribute to our understanding of concept acquisition. The first thing to note is that this new account
369 is strongly developmental. As mentioned in the introduction, concepts evolve over time – a five year old’s
370 concept of *love* is unlikely to be identical to that of a 15-year-old, which in turn is likely to be different from
371 the concept the individual will have at age 35. For any given concept, its characterisation in Eqn. 4 therefore
372 changes over time. In particular, concepts may initially be formed from partial information and additional
373 terms added as the modalities that provide such features develop, or other types of information becomes
374 available, reflecting the rapid development of conceptual structures seen in early childhood (Mandler, 2000;
375 Quinn and Eimas, 1997). The characterisation given by Eqn. 4, for any given concept, is therefore also
376 subject to development. Thus, it is possible to predict a developmental timeline given a hypothesis of
377 necessary constituents – that is, a concept can only be acquired once its constituent semantic pointers have
378 been acquired. It is worth pointing out that any theory of concept acquisition implicitly makes at least one
379 prediction in this sense: that the proposed cognitive mechanisms exist by the time children begin to acquire
380 the concepts in question. As noted previously for example, Dove (2011) has argued that the ability to form
381 metaphors develops too late to adequately be positioned at the core of abstract concept grounding (**although**
382 **metaphors can contribute to such concepts once available**). Similarly, the idea that concepts might be made
383 **of contextualised simulations (Barsalou, 1999; Barsalou and Wiemer-Hastings, 2005; Barsalou, 2009)**
384 **predicts that the necessary mechanisms to develop such simulations develops in a manner consistent with**
385 **AoA. Conversely, if a developmental timeline for simulation mechanisms is given⁶, it is then possible to**
386 **sketch how a concept develops from AoA onwards as the simulations it relies on mature.**

387 A historic problem for theories of embodied cognition is how to account for acquisition of concrete and
388 abstract concepts in a single mechanism. For example, while concrete *yellow* can be directly acquired from
389 the external world, the more abstract *lonely* requires interoceptive features, while *whatever* is arguably
390 linguistically mediated. Here, Eqn. 4 provides a starting point since it can form the basis for a measure of
391 how much of a given concept is grounded in simple, directly perceivable sensorimotor modalities in the
392 sense of Eqns. 1 and 2. In other words, how abstract a concept is is a function of how much of its substance
393 goes beyond simple sensorimotor grounding. This is essentially very similar to the previously mentioned
394 claims from the WAT theory (Borghi and Binkofski, 2014), which argues that more abstract concepts are
395 made up of more social aspects that are not related to an individual’s sensorimotor experience. At the
396 same time it extends this to include *any* source for aspects that are not of a simple external sensorimotor
397 type, including **not only more complex sensorimotor experiences related to linguistic usage of the concepts**
398 **(Zwaan, 2015; Dove, 2011; Barsalou et al., 2008) but also** interoceptive (Thill et al., 2014) features.

399 Because our characterisation in Eqn. 4 incorporates interoceptive features, the conceptual structure
400 it entails is subtly different from that of the commonly and often interchangeably used, adult-rated
401 concreteness or imageability scales (Reilly and Dean, 2007). By trying to provide a way to quantify how
402 much of a concept is grounded in a rich but direct sensorimotor experience, we measure the “groundability”
403 of a concept: the degree to which a concept is directly grounded in embodied processes. **Importantly,**
404 **these embodied processes include internal modalities, including affect and other interoceptive aspects: a**
405 **concept can thus be directly grounded even if it has no perceivable aspect in the external world.** Rather than
406 distinguishing between “concrete” and “abstract” concepts, then, we distinguish between concepts that

⁶ Thill and Svensson (2011) discuss the current lack of such a timeline in more detail and speculate that simulations may co-develop with dreams, with the implication being that the quality of dreams (which do not reach adult-levels of sophistication until the late teens) may serve as an indicator of the sophistication of internal models underlying simulations.

407 have a larger or smaller proportion of directly grounded components. Developing a groundability scale, in
408 particular one that can account for development, will be key to empirical tests of this account.

409 The mechanisms provided by SPA also raise important questions for subsequent work: for example,
410 since SPA uses vectors for the underlying representations, what might the distribution of these vectors be
411 when constructed in a bio-realistic fashion, and to what degree does this relate directly to our measure of
412 groundability? **Further, a developmental process that enriches concepts** over time with newly accessible
413 information from existing or new modalities effectively modifies the direction of the vector in space. This
414 might provide a quantitative measure for the amount of change that the introduction of a new cognitive
415 mechanism can induce in a concept.

416 Importantly, this approach is also consistent with the developmental literature. Sloutsky (2010), for
417 example, provides such an account of the neural mechanisms underlying concept learning, distinguishing
418 between statistically “dense” and “sparse” categories (the difference being the amount of redundant
419 information that a concept carries). Sloutsky relates these to different learning mechanisms – compression
420 mechanisms for dense, and selection mechanisms for sparse categories. Where abstract concepts (which,
421 in his terms are concepts that have no sensory target, such as “love”) are concerned, Sloutsky posits
422 an important role for the executive function, and therefore PFC. Taken together, these insights combine
423 into a developmental hypothesis of category learning: dense categories are easier to learn than sparse
424 because the required compression mechanisms develop earlier while the involvement of the executive
425 function in abstract concepts would predict a late acquisition due to the late maturation of the PFC (for a
426 much more detailed reasoning, see Sloutsky, 2010). The account we have provided here includes these
427 considerations in the precise neural mechanisms that SPA postulates to underlie semantic pointer formation
428 (Eliasmith, 2013), but it also extends them with a more explicit inclusion of embodied mechanisms
429 that have their own developmental timeline. **Our account also ties in with Barsalou’s idea of *situated***
430 ***conceptualisation* (Barsalou, 2009) and the suggestion that concepts are a “large collection of situational**
431 ***representations*” (Barsalou and Wiemer-Hastings, 2005, p. 156) since, as previously noted, SPA can**
432 **be seen as a computational implementation of Barsalou’s (1999) perceptual symbol system. A *situated***
433 ***conceptualisation* could be achieved by decompressing some of the semantic pointers (thus activating**
434 ***simulations of the corresponding sensorimotor experience*) that make up a given concept. Conversely a**
435 ***theory of what situated conceptualisations for a given concept need to contain can in turn provide insights***
436 ***into what aspects of (internal and external) sensorimotor experience might make up that concept, thus***
437 ***contributing to insights into the nature of Eqn. 4 for that concept.***

6 CONCLUSION

438 In sum, we have shown how developmental accounts of concept acquisition can include embodied theories
439 of cognition, without being forced to claim that all aspects of all concepts are necessarily grounded in some
440 sensorimotor experience. We have also highlighted the importance of understanding the term “sensorimotor”
441 experience as going beyond sensorimotor interaction with the *external* world: the inside matters just as
442 much. We refer to the extent to which a concept is richly embodied in this way as its *groundability*. Using
443 empirical data, we have shown both that the semantic features typically considered in developmental
444 studies are not sufficient to explain variability in AoA and, critically, that including BOI as a measure
445 which can be related to **sensorimotor experience** improves the results.

446 Our account unifies existing theories of embodied cognition in a single mechanism by highlighting how
447 cognitive mechanisms that develop comparatively late can enrich existing concepts. It also makes it clear

448 that concepts which have no components that are available early on can only develop later. It also suggests
449 that additional factors in AoA cover a range of attributes: (a) the complexity of the underlying concepts
450 in terms of how many modalities and features they aggregate, (b) the proportion of directly groundable
451 features, (c) the degree to which such features refer to aspects of the external sensorimotor experience,
452 (d) the development of necessary sophisticated mechanisms, and (e) the ability to communicate about
453 them. Thus, this theoretical account integrates research in embodied cognition and cognitive development,
454 paving, we hope, the way for future empirical tests of the interaction between groundability and concept
455 acquisition.

DISCLOSURE/CONFLICT-OF-INTEREST STATEMENT

456 The authors declare that the research was conducted in the absence of any commercial or financial
457 relationships that could be construed as a potential conflict of interest.

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A LIST OF DATA USED IN THE REGRESSION ANALYSES

Word	AoA (months)	CHILDES Frequency	Imageability	Valence	BOI
animal	23	396	575	6.48	
ankle	30	21	613	5.27	
apple	17	973	637	6.41	5.26
arm	21	354	593	5.34	5.7
aunt	24	196	567	6.39	4.73
baby	15	6227	608	8.22	5.59
bad	23	634	388	2.56	
banana	16	536	644	6.61	4.89
basement	31	77	571	4.67	3.29
basket	25	410	560	5.45	5.07
bath	17	492	601	7.33	4.8
beach	23	377	667	8.03	4.3
bear	19	2201	572	4.78	
bed	20	1663	635	7.51	6.27
bench	23	54	555	4.61	5.9
bib	20	216	488	5.57	3.9
bird	16	1128	614	7.27	5.17
black	29	665	589	5.39	
blanket	19	262	582	6.94	5.78
blue	22	2068	569	6.76	1.55
boat	18	389	631	7.79	5.7
book	16	4936	591	5.72	6.33
bottle	16	718	619	6.15	5.59
bowl	21	603	579	5.33	5.93
boy	20	3383	618	6.32	5.67
break	23	647	398	4.59	
broken	22	410	469	3.05	
broom	21	109	608	4.83	6.31
brother	28	242	589	7.11	
bucket	26	252	586	5.1	5.11
bunny	19	1379	585	7.24	
butter	22	421	603	5.33	4
butterfly	23	302	624	7.17	2.52
button	20	474	580	5.21	4.96
cake	22	519	624	7.26	5.9
candy	22	266	601	6.54	
car	25	2529	638	7.73	6.4
cereal	22	439	576	7.35	
chair	19	2016	610	5.08	
chalk	30	58	601	4.89	5.6
cheese	18	986	592	6.33	
chicken	22	749	619	6.87	3.67

461

Word	AoA (months)	CHILDES Frequency	Imageability	Valence	BOI
child	28	153	619	7.08	6.07
chin	22	124	608	5.29	4.4
chocolate	19	438	611	6.88	5.49
church	26	58	616	6.28	4.36
circus	31	155	586	7.3	
clean	23	1361	454	7.23	
clock	20	208	614	5.14	5.47
closet	26	174	525	5.21	2.96
clown	23	310	589	5.39	4.67
cold	19	992	531	4.02	
cook	23	309	504	6.16	
cookie	16	1300	600	7.6	5.15
corn	23	276	601	6	5.93
couch	23	272	536	6.78	5.86
country	31	64	539	5.93	
cow	19	848	632	5.57	
cup	19	1033	558	5.44	5.79
cut	26	701	460	3.64	
dance	22	349	510	7.38	
dark	25	274	586	4.71	
day	29	1793	526	6.66	1.87
dinner	22	627	570	7.16	
dirty	19	876	485	3.08	
doctor	23	357	600	5.2	3.37
dog	14	1385	636	7.57	6.4
doll	20	315	565	6.09	6.43
door	19	1250	599	5.13	
dress	23	366	595	6.41	
dump	30	289	528	3.21	
eat	19	5076	563	7.47	
egg	21	674	599	5.29	
elephant	31	593	616	6.48	1.93
eye	16	543	603	5.86	5.47
face	23	1299	581	6.39	5.8
fall	22	933	547	4.09	
farm	27	346	560	5.53	4.1
finish	29	830	437	7.8	
first	27	1927	388	6.89	1.27
fish	21	1175	615	6.04	5.73
flag	26	51	607	6.02	
flower	19	424	618	6.64	4.33
food	23	1149	539	7.65	6.4
foot	19	899	597	5.02	5.73

463

Word	AoA (months)	CHILDES Frequency	Imageability	Valence	BOI
fork	21	205	598	5.29	6.13
friend	27	591	587	7.74	5.53
frog	31	417	617	5.71	5.03
game	27	664	521	6.98	3.97
garbage	23	278	596	2.98	4.07
garden	30	191	635	6.71	5.22
gentle	30	268	422	7.31	
girl	22	2264	634	6.87	5.13
give	22	3477	383	7.13	
glass	23	255	585	4.75	5.83
good	22	11108	374	7.47	
grass	22	293	602	6.12	5.3
green	25	1869	609	6.18	1.43
hair	19	1515	580	5.56	5.8
hammer	23	284	618	4.88	5.37
hand	19	1607	598	5.95	5.87
happy	23	983	511	8.21	
hard	28	1049	460	5.22	
hat	18	1479	562	5.46	6.07
hate	31	58	462	2.12	
head	21	1719	593	6.63	6.03
heavy	23	335	495	3.69	
hen	30	85	597	5.1	4.31
hide	25	312	430	4.32	
high	27	469	463	6.62	
home	22	1770	599	7.91	4.23
horse	19	646	624	5.89	
hose	25	60	572	5.25	4.47
house	22	2458	606	7.26	
hungry	23	706	503	3.58	
hurt	24	922	465	1.9	
ice	22	413	635	5.92	5.79
jar	30	109	571	5.21	
jelly	25	134	590	5.66	
juice	16	1845	593	6.79	5.9
kick	23	205	551	4.31	
kiss	21	896	633	8.26	
knee	21	131	597	5.03	5.17
knife	30	145	633	3.62	6.07
lamb	26	181	614	5.89	5
lamp	28	56	575	5.41	5.48
leg	22	385	601	5.71	5.96
like	25	17537	352	7.52	

464

Word	AoA (months)	CHILDES Frequency	Imageability	Valence	BOI
lion	23	412	626	5.57	1.93
listen	29	504	378	5.93	
loud	27	317	448	4.77	
love	23	1434	569	8.72	2
lunch	24	751	602	7.21	4.8
mad	29	293	479	2.44	
man	22	1161	567	6.73	6.3
me	20	14537	430	8.06	
meat	24	250	618	6.66	6
medicine	23	200	551	5.67	4.8
milk	19	1346	638	5.95	5.3
money	22	748	604	7.59	5.1
moon	21	512	585	6.74	2.33
mouth	19	1790	613	5.46	
movie	29	316	571	6.86	3.1
nail	27	72	588	5.14	5.97
napkin	23	248	582	4.84	5.39
necklace	24	95	606	6.39	5.19
nice	25	3259	375	6.55	
night	23	1114	607	6.06	1.53
noisy	28	133	215	5.02	
nose	16	1674	605	4.71	5.43
nurse	31	195	617	6.08	5.3
old	30	977	478	3.31	
orange	22	1114	626	6.47	5.15
oven	27	157	599	5.71	4.78
owl	22	258	595	5.8	4.17
paint	26	263	567	5.62	5.3
paper	21	1354	590	5.2	5.93
party	25	422	596	7.86	4.39
pencil	25	297	607	5.22	5.96
penny	25	85	609	5.06	
people	26	1404	548	7.33	
person	31	338	562	6.32	
pig	19	670	635	5.07	5.23
pillow	21	215	624	7.92	5.78
plant	25	198	605	5.98	5.63
plate	23	351	527	5.3	5.5
play	23	5885	498	8.1	
pony	26	106	642	6	
pool	20	200	577	7.7	5.37
poor	31	468	447	2.28	
porch	31	37	586	6.14	4.57

465

Word	AoA (months)	CHILDES Frequency	Imageability	Valence	BOI
present	23	281	481	6.95	3.93
present	23	281	481	6.95	3.93
pretty	22	2185	520	7.75	
puppy	19	693	635	7.56	
quiet	25	295	426	5.58	
radio	26	86	613	6.73	4.04
rain	20	322	618	5.08	4.27
red	23	2097	585	6.41	1.61
refrigerator	25	221	612	6.14	4.48
rock	21	360	612	5.56	
roof	30	101	604	5.4	3.14
room	23	1548	545	5.52	4.93
sad	27	399	419	1.61	
salt	22	101	570	5.56	5.4
school	23	1550	599	4.36	4.69
scissors	25	143	609	5.05	5.48
sheep	23	438	596	6.44	5.31
shower	22	102	615	7.04	4.33
sick	26	316	456	1.9	
sing	25	953	527	6.77	
sister	29	270	613	7.46	
skate	31	28	563	6.6	4.1
sky	23	361	618	7.37	1.53
sleep	22	863	530	7.2	3.1
slow	30	213	377	3.93	
smile	27	123	615	8.16	2.73
snow	23	650	597	7.08	
soap	20	193	600	5.97	6.27
sofa	31	49	597	6.53	5.27
soft	26	300	476	7.12	
soup	23	342	604	6.25	5.7
spoon	19	784	584	5.93	5.97
star	24	390	623	7.27	2.23
stop	24	1600	452	3.96	
store	22	801	506	5.93	4.23
story	23	1205	491	6.63	2.56
stove	26	123	592	4.98	
street	25	348	577	5.22	4.2
sun	23	569	639	7.55	2.13
table	23	1391	582	5.22	5.04
taste	29	397	425	6.66	
teacher	29	189	575	5.68	
think	31	10902	384	6.41	

Word	AoA (months)	CHILDES Frequency	Imageability	Valence	BOI
thirsty	25	236	482	3.61	
tickle	22	412	492	6.86	4.19
tiger	23	240	606	5.89	1.67
time	31	3382	413	5.31	2.03
tired	25	751	419	3.28	
tooth	19	169	624	5.19	5.9
touch	26	912	456	6.31	
towel	22	380	570	5.75	6.22
toy	19	885	569	7	6.17
train	20	1120	593	5.59	5.14
trash	29	196	599	2.67	5.2
466 tray	31	179	550	5.1	5.29
tree	19	1011	622	6.32	5.53
truck	18	1239	621	5.47	
turtle	23	308	564	6.78	2.93
watch	25	1789	525	5.78	
water	19	2570	632	6.61	
wet	21	597	509	5.57	
white	27	873	566	6.47	1.5
window	23	568	602	5.91	3.52
wish	31	177	399	7.09	1.87
wolf	27	116	610	5	4.7
work	23	1266	458	3.96	2.7
yellow	25	1429	598	5.61	
zipper	22	162	632	5.39	5.04

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FIGURES

Provisional

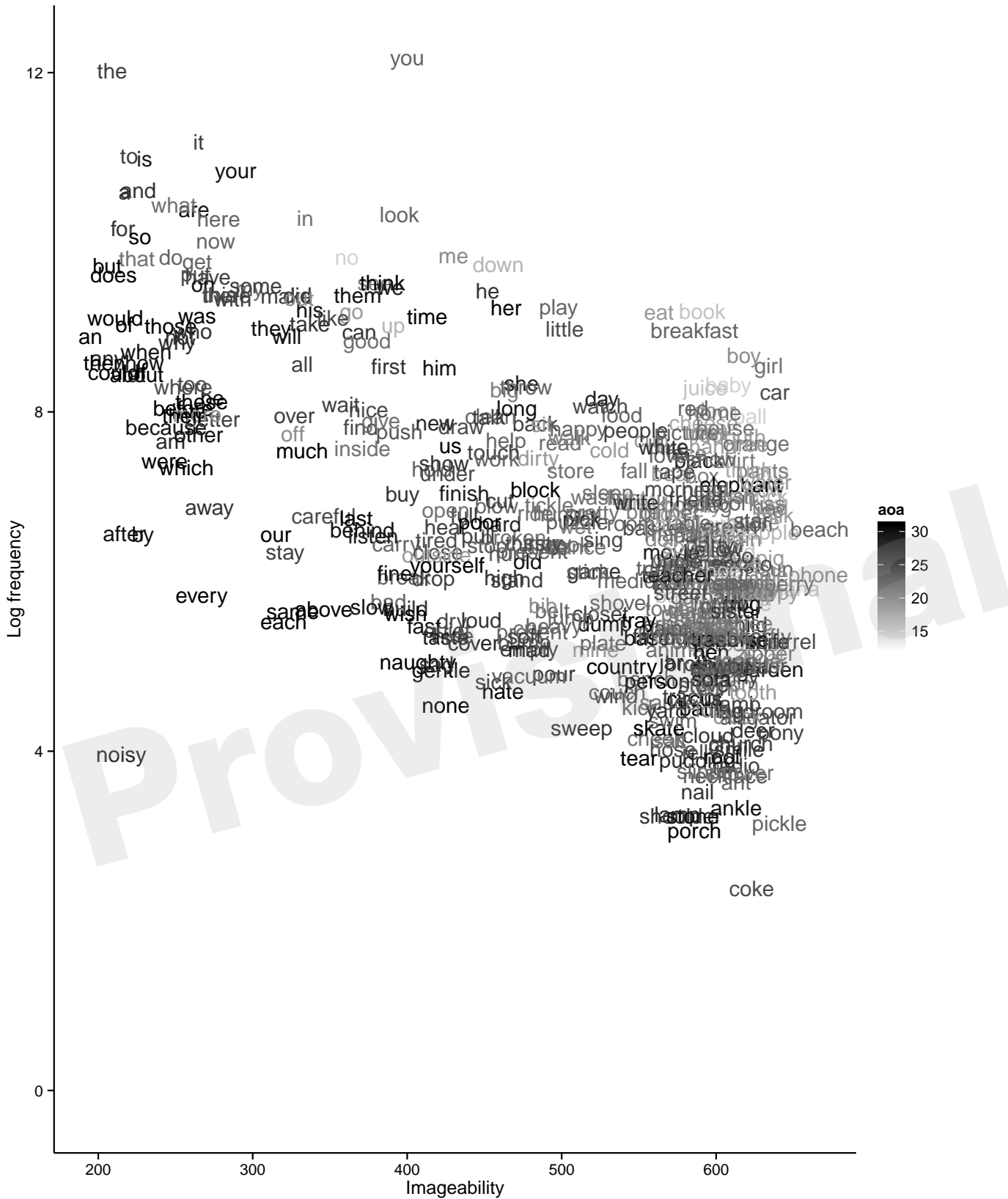


Figure 1: AoA of early concepts plotted by log frequency and imageability. Darker text indicates later AOI

TABLES

Table 1. Pearson correlations between regression predictors. * $p < .05$, *** $p < .001$.

	BOI	Imageability	Frequency
Imageability	0.44***		
Frequency	0.18	-0.45***	
Valence	-0.21*	0.23***	0.22***

Table 2. Conceptual features model parameters and significance tests ($N = 239$). ** $p < .01$, *** $p < .001$.

	β	t	p	F	df	p
Overall model				37.73	(4,234)	< .0001***
Log frequency	-1.48	-6.74	< .0001***			
Imageability	-0.022	-7.33	< .0001***			
Valence	0.055	0.34	.74			
Log frequency x imageability	-0.0065	-3.18	.0017**			
R^2	0.39					
Adjusted R^2	0.38					

Table 3. BOI model parameters and significance tests ($N = 151$). * $p < .05$, ** $p < .01$, *** $p < .001$.

	β	t	p	F	df	p
Overall model				21.32	(5,145)	< .001***
Log frequency	-0.93	-1.78	.078			
Imageability	-0.013	-2.22	.028*			
Valence	-0.19	-0.76	.45			
Body-object interaction	-0.88	-4.49	< .001***			
Log frequency x imageability	-0.010	-1.99	.049*			
R^2	0.42					
Adjusted R^2	0.40					

Table 4. Conceptual features model parameters and significance tests fit to dataset used for BOI model ($N = 151$). $**p < .01$, $***p < .001$.

	β	t	p	F	df	p
Overall model				19.11	(4,146)	$< .001^{***}$
Log frequency	-0.59	-1.07	.28			
Imageability	-0.022	-3.59	$< .001^{***}$			
Valence	0.037	0.27	.14			
Log frequency x imageability	-0.014	-2.62	.0099**			
R^2	0.39					
Adjusted R^2	0.38					

Provisional